

Numerical Methods for PDEs

Integral Equation Methods, Lecture 6
Discretization and Quadrature

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Outline

Everything is Galerkin

Reminder of 1-D and 3-D 2nd Kind

Collocation is Galerkin

Single Point Quadrature

Quadrature

Nystrom is Galerkin

N point quadrature

Multidimensional Quadrature

“Volume” Integral Equations

First Kind

$$\Psi(x) = \int_{-1}^1 G(x, x') \sigma(x') dx' \quad x \in [-1, 1]$$

Second Kind

$$\Psi(x) = \sigma(x) + \int_{-1}^1 G(x, x') \sigma(x') dx' \quad x \in [-1, 1]$$

Equation Examples

“Surface” 3-D Potential Integral Equations

First Kind

$$u_{\Gamma}(\vec{x}) = \int_{\Gamma} \frac{1}{\|\vec{x} - \vec{x}'\|} \sigma(\vec{x}') d\Gamma' \quad \vec{x} \in \Gamma$$

Second Kind

$$\frac{\partial u_{\Gamma}(\vec{x})}{\partial n_{\vec{x}}} = 2\pi\sigma(\vec{x}) + \int_{\Gamma} \frac{\partial}{\partial n_{\vec{x}}} \frac{1}{\|\vec{x} - \vec{x}'\|} \sigma(\vec{x}') d\Gamma' \quad \vec{x} \in \Gamma$$

2nd Kind

Discretization

Collocation

Introduce a Basis Representation

$$\sigma_n(x) = \sum_{i=1}^n \sigma_{ni} \varphi_i(x)$$

Make Residual Zero at Collocation Points x_i

$$\Psi(x_i) = \sum_{i=1}^n \sigma_{ni} \varphi_i(x_i) - \int_{-1}^1 G(x_i, x') \sum_{i=1}^n \sigma_{ni} \varphi_i(x') dx'$$

Make Residual orthogonal to basis

$$\int_{P_i} \varphi_i(x) \Psi(x) dx =$$

$$\int_{P_i} \varphi_i(x) \sum_{j=1}^n \sigma_{nj} \varphi_j(x) dx$$

$$+ \int_{P_i} \varphi_i(x) \sum_{j=1}^n \sigma_{nj} \int_{P_j} G(x, x') \varphi_j(x') dx' dx$$

Note: P_i is the support of $\varphi_i(x)$.

Discretization

Assume Orthonormal Basis

Orthogonality

$$\int_{P_i \cup P_j} \varphi_i(x) \varphi_j(x) dx = 0$$

Normalization

$$\int_{P_i} \varphi_i(x) \varphi_i(x) dx = 1$$

Collocation = Galerkin with one point quadrature

One point quadrature implies

$$\int_{P_i} \varphi_i(x) \Psi(x) dx \approx w_i \varphi_i(x_i) \Psi(x_i)$$

x_i = quadrature point

w_i = quadrature weight

Discretization

One point quadrature implies

$$\int_{P_i} \varphi_i(\mathbf{x}) \sum_{j=1}^n \sigma_{nj} \varphi_j(\mathbf{x}) d\mathbf{x} \approx w_i \varphi_i(\mathbf{x}_i) \sum_{j=1}^n \sigma_{nj} \varphi_j(\mathbf{x}_i)$$

$$\int_{P_i} \varphi_i(\mathbf{x}) \sum_{j=1}^n \sigma_{nj} \int_{P_j} G(\mathbf{x}, \mathbf{x}') \varphi_j(\mathbf{x}') d\mathbf{x}' d\mathbf{x} \approx$$

$$w_i \varphi_i(\mathbf{x}_i) \sum_{j=1}^n \sigma_{nj} \int_{P_j} G(\mathbf{x}_i, \mathbf{x}') \varphi_j(\mathbf{x}') d\mathbf{x}'$$

Discretization

Putting together

$$\begin{aligned} w_i \varphi_i(x_i) \Psi(x_i) = & \\ & w_i \varphi_i(x_i) \sum_{j=1}^n \sigma_{nj} \varphi_j(x_i) \\ & + w_i \varphi_i(x_i) \sum_{j=1}^n \sigma_{nj} \int_{P_j} G(x_i, x') \varphi_j(x') dx' \end{aligned}$$

Discretization

Dividing by $w_i \varphi_i(x_i)$ and reorganizing

$$\Psi(x_i) = \sum_{j=1}^n \sigma_{nj} \varphi_j(x_i) + \int \sum_{j=1}^n \sigma_{nj} G(x_i, x') \varphi_j(x') dx'$$

which is precisely the collocation equations.

$$\int_{P_i} \varphi_i(\mathbf{x}) \sum_{j=1}^n \sigma_{nj} \int_{P_j} G(\mathbf{x}, \mathbf{x}') \varphi_j(\mathbf{x}') d\mathbf{x}' d\mathbf{x} \approx$$

$$w_i \varphi_i(\mathbf{x}_i) \sum_{j=1}^n \sigma_{nj} \int_{P_j} G(\mathbf{x}_i, \mathbf{x}') \varphi_j(\mathbf{x}') d\mathbf{x}'$$

or

$$\sum_{j=1}^n \sigma_{nj} w_j \varphi_j(\mathbf{x}_j) \int_{P_i} G(\mathbf{x}', \mathbf{x}_j) \varphi_i(\mathbf{x}') d\mathbf{x}'$$

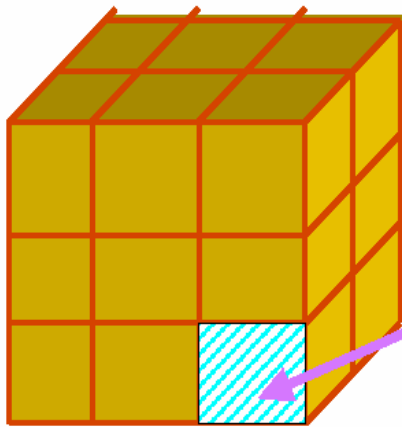
Qualocation

Discretization

3-D Piecewise Constant Basis

$$\frac{\partial u_{\Gamma}(\vec{x})}{\partial n_{\vec{x}}} = 2\pi\sigma(\vec{x}) + \int_{\Gamma} \frac{\partial}{\partial n_{\vec{x}}} \frac{1}{\|\vec{x} - \vec{x}'\|} \sigma(\vec{x}') d\Gamma'$$

Discretize Surface into
Panels



Panel j

$$\text{Represent } \sigma(x) \approx \sum_{i=1}^n \alpha_i \underbrace{\varphi_i(x)}_{\text{Basis Functions}}$$

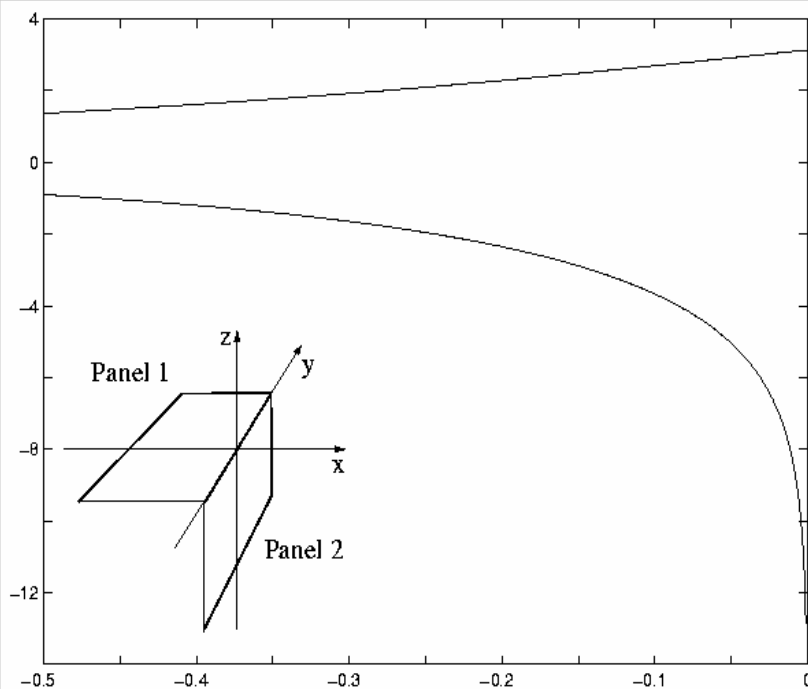
$$\varphi_j(x) = 1 \quad \text{if } x \text{ is on panel } j$$

$$\varphi_j(x) = 0 \quad \text{otherwise}$$

Discretization

Qualocation

Integration Difficulty



top curve:

$$\int_{\Gamma} \frac{\partial}{\partial n_{\vec{x}}} \frac{1}{\|\vec{x} - \vec{x}'\|} d\Gamma'$$

Bottom curve:

$$\int_{\Gamma} \frac{\partial}{\partial n_{\vec{x}'}} \frac{1}{\|\vec{x} - \vec{x}'\|} d\Gamma'$$

Set quadrature points = collocation points

$$\Psi(x_1) = \sigma_{n1} + \sum_{j=1}^n w_j G(x_1, x_j) \sigma_{nj}$$

$$\Psi(x_n) = \sigma_{n1} + \sum_{j=1}^n w_j G(x_n, x_j) \sigma_{nj}$$

System of n equations in n unknowns

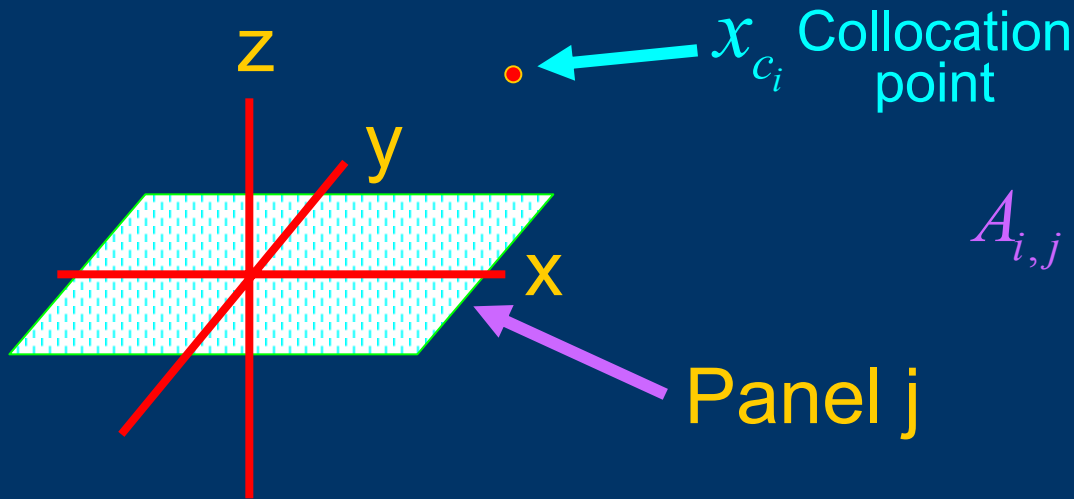
Collocation equation per quad/colloc point

Nystrom = Galerkin with n point quadrature

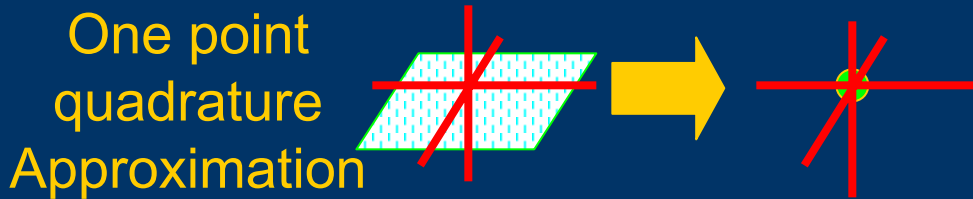
2-D Integration (from 3-D problems)

Reminder

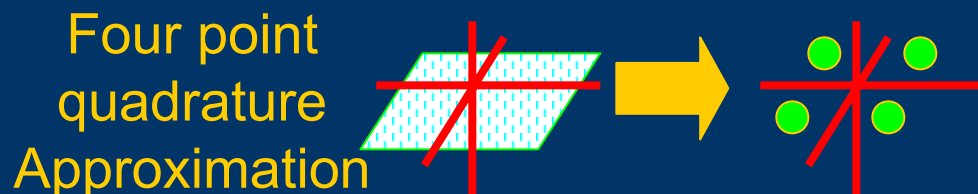
Calculating Matrix Elements



$$A_{i,j} = \int_{\text{panel } j} G(x_{c_i}, x') dS'$$



$$A_{i,j} \approx \text{Area} \cdot G(x_{c_i}, x_{\text{centroid}_j})$$



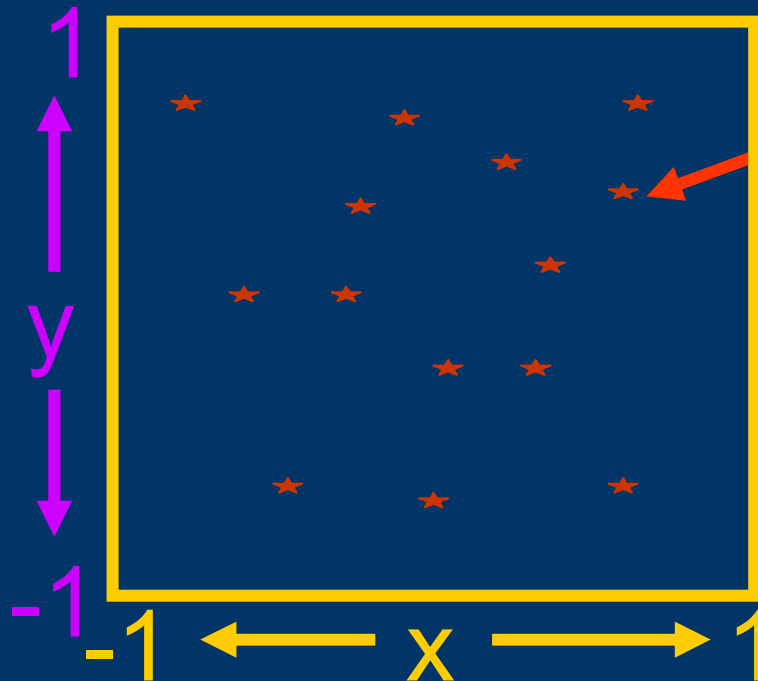
$$A_{i,j} \approx \sum_{j=1}^4 \frac{\text{Area}}{4} * G(x_{c_i}, x_{\text{point}_j})$$

Symmetrically Normalized 2-D Problem

Quadrature Scheme

General n-point formula

$$\int_{-1}^1 \int_{-1}^1 f(x, y) dx dy \approx \sum_{i=1}^n w_i f(x_i, y_i)$$



n points, n weights
2n parameters

Symmetrically Normalized 2-D Problem

Quadrature Scheme

2-D Gaussian Quadrature

Exactness for l-th order polys

$$\int_{-1}^1 \int_{-1}^1 p_l(x, y) dx dy = \sum_{i=1}^n w_i p_l(x_i, y_i)$$

l-th order 2-D poly definition

$$p_l(x, y) = \sum_{(i+j) \leq l} \alpha_{i,j} x^i y^j$$

$$\text{Number of terms} = \frac{(l+1)(l+2)}{2}$$

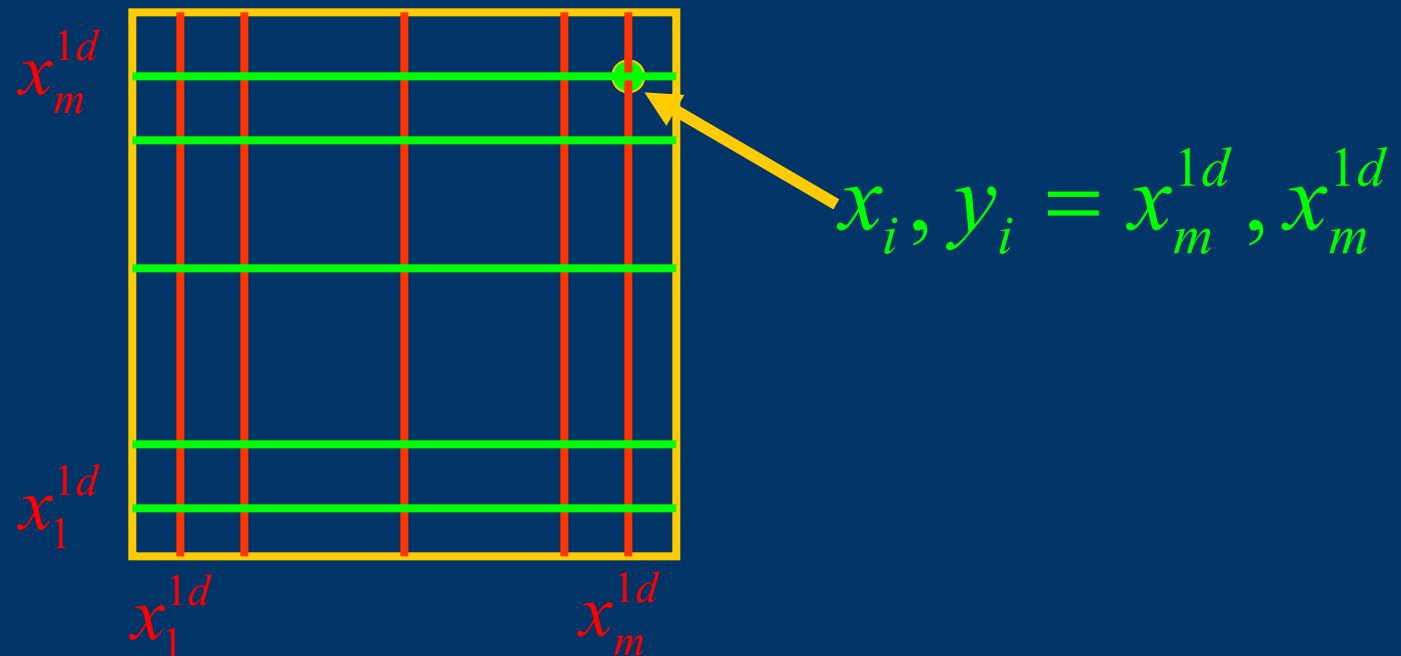
Symmetrically Normalized 2-D Problem

Quadrature Scheme

Product Method

1) Get a 1-d formula $\int_{-1}^1 f(x) dx \approx \sum_{i=1}^m w_i^{1d} f(x_i^{1d})$

2) Form a “product” grid



3) Determine the weights

$$\int_{-1}^1 \int_{-1}^1 f(x, y) dx \approx \sum_{i=1}^m \sum_{j=1}^m w_{i,j} f(x_i^{1d}, x_j^{1d})$$

$$w_{i,j} = w_i^{1d} w_j^{1d}$$

Note that $n = m \times m$

Symmetrically Normalized 2-D Problem

Quadrature Scheme

Product Method Theorem

Theorem: The product method is exact
for all 2-d polys up to order $2m$

Proof:

Using the l -th order poly def

$$\int_{-1}^1 \int_{-1}^1 p_m(x, y) dx dy = \int_{-1}^1 \int_{-1}^1 \sum_{(i+j) \leq m} \alpha_{i,j} x^i y^j dx dy$$

Using the properties of integration

$$\begin{aligned} \int_{-1}^1 \int_{-1}^1 \sum_{(i+j) \leq m} \alpha_{i,j} x^i y^j dx dy &= \sum_{(i+j) \leq m} \alpha_{i,j} \int_{-1}^1 \left(\int_{-1}^1 x^i dx \right) y^j dy \\ &= \sum_{(i+j) \leq m} \alpha_{i,j} \left(\int_{-1}^1 x^i dx \right) \left(\int_{-1}^1 y^j dy \right) \end{aligned}$$

Symmetrically Normalized 2-D Problem

Quadrature Scheme

Product Theorem Cont.

Since the 1-d quadrature is exact for polys
of order less than $2m$

$$\sum_{(i+j) \leq m} \alpha_{i,j} \left(\int_{-1}^1 x^i dx \right) \left(\int_{-1}^1 y^j dy \right) =$$

$$\sum_{(i+j) \leq m} \alpha_{i,j} \left(\sum_{k=1}^m w_k^{1d} \left(x_k^{1d} \right)^i \right) \left(\sum_{l=1}^m w_l^{1d} \left(x_l^{1d} \right)^j \right)$$

Rearranging the sums

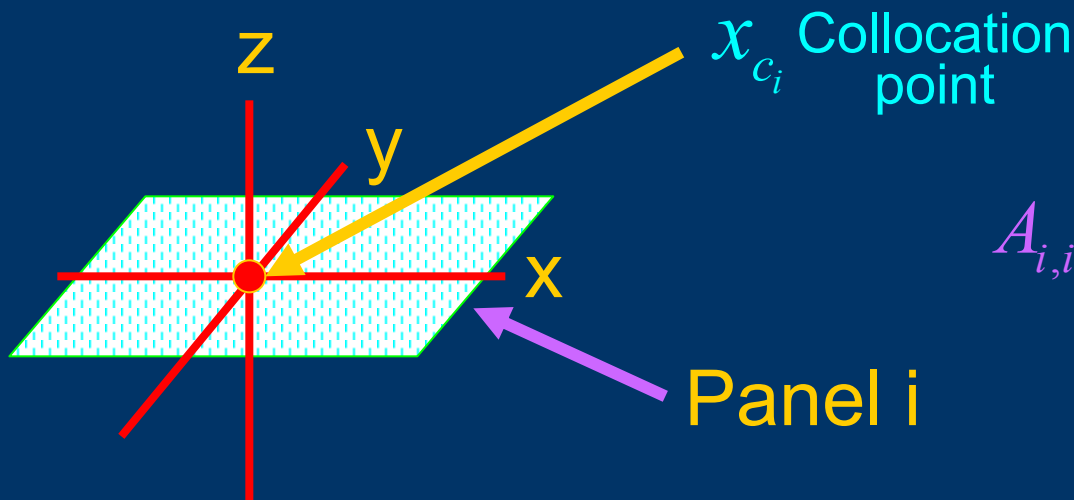
$$\begin{aligned} \sum_{(i+j) \leq m} \alpha_{i,j} \left(\sum_{k=1}^m w_k^{1d} \left(x_k^{1d} \right)^i \right) \left(\sum_{l=1}^m w_l^{1d} \left(x_l^{1d} \right)^j \right) &= \\ \sum_{l=1}^m \sum_{k=1}^m w_k^{1d} w_l^{1d} \sum_{(i+j) \leq m} \alpha_{i,j} \left(x_k^{1d} \right)^i \left(x_l^{1d} \right)^j &= \\ \sum_{l=1}^m \sum_{k=1}^m w_k^{1d} w_l^{1d} p_m \left(x_k^{1d}, x_l^{1d} \right) & \end{aligned}$$

Which proves the theorem

3-D Laplace's Equation

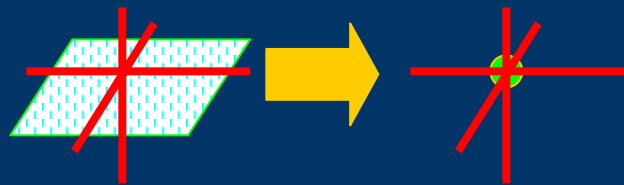
Basis Function Approach

Calculating "Self-Term"



$$A_{i,i} = \int_{\text{panel } i} \frac{1}{\|x_{c_i} - x'\|} dS'$$

One point quadrature Approximation



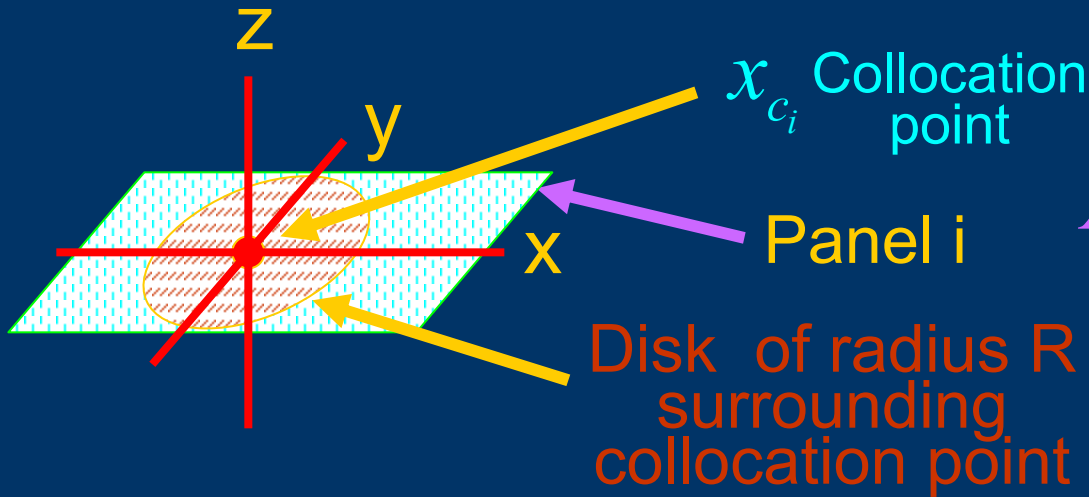
$$A_{i,i} \approx \frac{\text{Panel Area}}{\underbrace{\|x_{c_i} - x_{c_i}\|}_0}$$

$$A_{i,i} = \int_{\text{panel } i} \frac{1}{\|x_{c_i} - x'\|} dS' \text{ is an integrable singularity}$$

3-D Laplace's Equation

Basis Function Approach

Calculating "Self-Term"
Tricks of the trade



$$A_{i,i} = \int_{\text{panel } i} \frac{1}{\|x_{c_i} - x'\|} dS'$$

Integrate in two pieces

$$A_{i,i} = \int_{\text{disk}} \frac{1}{\|x_{c_i} - x'\|} dS' + \int_{\text{rest of panel}} \frac{1}{\|x_{c_i} - x'\|} dS'$$

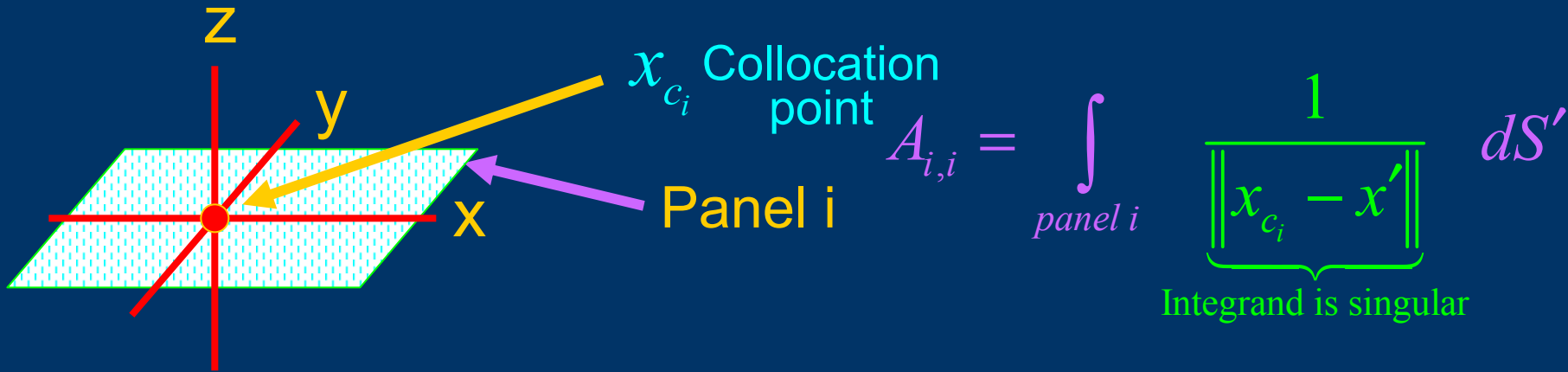
Disk Integral has singularity but has analytic formula

$$\int_{\text{disk}} \frac{1}{\|x_{c_i} - x'\|} dS' = \int_0^R \int_0^{2\pi} \frac{1}{r} r dr d\theta = 2\pi R$$

3-D Laplace's Equation

Basis Function Approach

Calculating "Self-Term"
Other Tricks of the trade



- 1) If panel is a flat polygon, analytical formulas exist
- 2) Curve panels can be handled with projection