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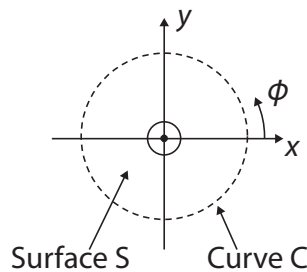
6.641 Electromagnetic Fields, Forces, and Motion
Spring 2005

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Problem Set 2 - Solutions

Problem 2.1

A

Figure 1: Surface S and contour C for using Ampere's law (Image by MIT OpenCourseWare.)

Step 1: Find field of z -directed line current, \vec{I} , at $x = y = 0$.

$$\vec{I} = I\hat{i}_z$$

By symmetry: $\vec{H} = H_\phi\hat{i}_\phi$ in cylindrical coordinates. By Ampere:

$$\oint_C \vec{H} \cdot d\vec{l} = \underbrace{\int_S \vec{J} \cdot d\vec{a}}_{\text{current going through } S}$$

$$(2\pi r)H_\phi = I$$

$$H_\phi = \frac{I}{2\pi r}\hat{i}_\phi \tag{1}$$

$$\hat{i}_\phi = \frac{-y}{\sqrt{x^2 + y^2}}\hat{i}_x + \frac{x}{\sqrt{x^2 + y^2}}\hat{i}_y$$

$$\vec{H} = \frac{I}{2\pi(x^2 + y^2)}(-y\hat{i}_x + x\hat{i}_y)$$

Step 2: Find solution by adding two translated \vec{H} fields:

$$\begin{aligned} \vec{H}_{\text{total}} &= \vec{H}_{I_1} + \vec{H}_{I_2} \\ &= \frac{I_1}{2\pi [x^2 + (y - \frac{d}{2})^2]} \left[-(y - \frac{d}{2})\hat{i}_x + x\hat{i}_y \right] + \frac{I_2}{2\pi [x^2 + (y + \frac{d}{2})^2]} \left[-(y + \frac{d}{2})\hat{i}_x + x\hat{i}_y \right] \end{aligned}$$

B

Step 3: We want field in $y = 0$ plane so $y \rightarrow 0$.

i

$$I_1 = I, I_2 = 0$$

$$\vec{H}_{\text{tot}} = \frac{I}{2\pi(x^2 + \frac{d^2}{4})} \left[\frac{d}{2}\hat{i}_x + x\hat{i}_y \right]$$

ii

$$I_1 = I, I_2 = I$$

$$\vec{H}_{\text{tot}} = \frac{I}{\pi(x^2 + \frac{d^2}{4})} [x\hat{i}_y]$$

iii

$$I_1 = I, I_2 = -I$$

$$\vec{H}_{\text{tot}} = \frac{I}{2\pi(x^2 + \frac{d^2}{4})} [d\hat{i}_x]$$

C

$$\vec{F} = q\vec{v} \times (\mu_0\vec{H})$$

so

$$d\vec{F} = dq \left[\vec{v} \times (\mu_0\vec{H}) \right]$$

In our problem the line current is a moving line charge, so $dq = \lambda dl$

$$d\vec{F} = \lambda\vec{v} \times [\mu_0\vec{H}] dl = \vec{I} \times (\mu_0\vec{H}) dl$$

$$\vec{F} = \int_0^L \vec{I} \times (\mu_0\vec{H}) dl = (\vec{I} \times \mu_0\vec{H})L$$

So

$$\frac{\text{Force}}{\text{Length}} = \vec{I} \times (\mu_0\vec{H})$$

We don't need to know \vec{H} since I_1 cannot exert a net force on itself. So we need a field of I_2

$$\vec{H} = \frac{I_2 \left[-\left(y + \frac{d}{2}\right)\hat{i}_x + x\hat{i}_y \right]}{2\pi \left(x^2 + \left(y + \frac{d}{2}\right)^2 \right)}$$

I_1 is at $x = 0, y = \frac{d}{2}$, so $x \rightarrow 0, y \rightarrow \frac{d}{2}$ above.

$$\vec{H} = \frac{-I_2 d \hat{i}_x}{2\pi d^2} = \frac{-I_2 \hat{i}_x}{2\pi d}$$

$$\frac{\text{Force}}{\text{Length}} = (\vec{I}_1) \times (\mu_0\vec{H}) = (I_1\hat{i}_z) \times \left(\frac{-\mu_0 I_2}{2\pi d} \right) \hat{i}_x$$

$$= \frac{-\mu_0 I_1 I_2 \hat{i}_y}{2\pi d}$$

$$(i) \quad I_1 = I, \quad I_2 = 0$$

$$\frac{\text{Force}}{\text{Length}} = 0$$

$$(ii) \quad I_1 = I, \quad I_2 = I$$

$$\frac{\text{Force}}{\text{Length}} = \frac{-\mu_0 I^2 \hat{i}_y}{2\pi d}$$

$$(iii) \quad I_1 = I, \quad I_2 = -I$$

$$\frac{\text{Force}}{\text{Length}} = +\frac{\mu_0 I^2 \hat{i}_y}{2\pi d}$$

Problem 2.2

A

The idea here is similar to applying the chain rule in a 1D problem

$$\frac{d}{dx} \left(\frac{1}{f(x)} \right) = \left[\frac{d}{df} \left(\frac{1}{f(x)} \right) \right] \left[\frac{df}{dx} \right] = \frac{-f'(x)}{f^2(x)}$$

$f(x)$ corresponds to $|\vec{r} - \vec{r}'|$. So, by diff. $f(x)$ we get part of the answer to the derivative of $\frac{1}{f(x)}$. But we can just do it directly too.

$$|\vec{r} - \vec{r}'| = \sqrt{(x - x')^2 + (y - y')^2 + (z - z')^2}$$

$$\nabla \left[\frac{1}{|\vec{r} - \vec{r}'|} \right] = \hat{i}_x \frac{\partial}{\partial x} \left[\frac{1}{|\vec{r} - \vec{r}'|} \right] + \hat{i}_y \frac{\partial}{\partial y} \left[\frac{1}{|\vec{r} - \vec{r}'|} \right] + \hat{i}_z \frac{\partial}{\partial z} \left[\frac{1}{|\vec{r} - \vec{r}'|} \right]$$

So we can apply the trick above by just considering x , y , and z components separately.

$$\begin{aligned} \frac{\partial}{\partial x} |\vec{r} - \vec{r}'| &= \frac{\partial}{\partial x} \left(\sqrt{(x - x')^2 + (y - y')^2 + (z - z')^2} \right) \\ &= \frac{x - x'}{\sqrt{(x - x')^2 + (y - y')^2 + (z - z')^2}} \\ &= \frac{x - x'}{|\vec{r} - \vec{r}'|} \end{aligned}$$

Similarly, $\frac{\partial}{\partial y} |\vec{r} - \vec{r}'| = \frac{y - y'}{|\vec{r} - \vec{r}'|}$ and $\frac{\partial}{\partial z} |\vec{r} - \vec{r}'| = \frac{z - z'}{|\vec{r} - \vec{r}'|}$.

$$\frac{\partial}{\partial x} \left(\frac{1}{|\vec{r} - \vec{r}'|} \right) = \frac{-\frac{\partial}{\partial x} |\vec{r} - \vec{r}'|}{|\vec{r} - \vec{r}'|^2}$$

and so on for y and z .

$$|\vec{r} - \vec{r}'|^2 = (x - x')^2 + (y - y')^2 + (z - z')^2$$

so:

$$\nabla \left[\frac{1}{|\vec{r} - \vec{r}'|} \right] = \frac{-(x - x')\hat{i}_x}{[(x - x')^2 + (y - y')^2 + (z - z')^2]^{\frac{3}{2}}} + \dots \text{similar terms for } y \text{ and } z$$

Denominators = $|\vec{r} - \vec{r}'|^{\frac{3}{2}}$. Thus,

$$\begin{aligned} \nabla \left[\frac{1}{|\vec{r} - \vec{r}'|} \right] &= \frac{-(\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} = \frac{-1}{|\vec{r} - \vec{r}'|^2} \frac{(\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|} \\ &= \frac{-\hat{i}_{r'r}}{|\vec{r} - \vec{r}'|^2} \end{aligned}$$

B

Follows from (A) immediately by substitution. Remember ∇ is derived in terms of unprimed x, y, z . ∇ does not affect x', y', z' .

C

$$\Phi(\vec{r}) = \int_{V'} \frac{\rho(\vec{r}')dV'}{4\pi\epsilon_0|\vec{r} - \vec{r}'|}$$

$\rho(\vec{r}')$ = charge density in $\frac{C}{m^3}$. We have λ in units of $\frac{C}{m}$. In this sense, $\rho \rightarrow \infty$ at the ring. We can represent this in cylindrical coordinates by $\rho(\vec{r}') = \lambda_0\delta(z)\delta(r - a)$. Then we can evaluate the triple integral

$$\int \int \int \frac{\lambda_0\delta(z)\delta(r - a)rd\phi d\theta dr}{4\pi\epsilon_0|\vec{r} - \vec{r}'|}$$

But, we can skip that unnecessary work by simply considering infinitesimal charges $(ad\phi)\lambda_0$ around the ring.

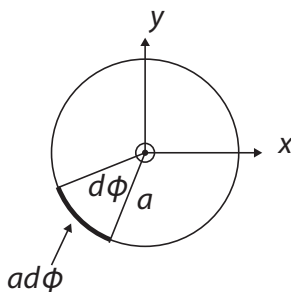


Figure 2: A ring of line charge with infinitesimal charge elements. (Image by MIT OpenCourseWare.)

We only care about z axis in this as well, so, by symmetry, there is no field in x and y directions.

$$\Phi(\vec{r}) = \int_0^{2\pi} \frac{\lambda_0(ad\phi)}{4\pi\epsilon_0 \underbrace{(a^2 + z^2)^{\frac{1}{2}}}_{\text{distance from the charge } \lambda_0 ad\phi \text{ to the point } z \text{ on the } z\text{-axis}}}$$

$$\Phi(\vec{r}) = \frac{\lambda_0 a}{2\epsilon_0(a^2 + z^2)^{\frac{1}{2}}}$$

on z -axis.

$$\vec{E} = -\nabla\Phi(\vec{r}) = -\left(\hat{i}_x \frac{\partial}{\partial x}\Phi + \hat{i}_y \frac{\partial}{\partial y}\Phi + \hat{i}_z \frac{\partial}{\partial z}\Phi\right)$$

$$\vec{E} = -\hat{i}_z \frac{\partial}{\partial z} \left(\frac{\lambda_0 a}{2\epsilon_0(a^2 + z^2)^{\frac{1}{2}}} \right)$$

$$\vec{E} = \hat{i}_z \frac{a\lambda_0 z}{2\epsilon_0(a^2 + z^2)^{\frac{3}{2}}}$$

Using Eq. (5) with z component only (symmetry) and with $\rho(\vec{r}')dV' \rightarrow \lambda_0 a d\phi$

$$\begin{aligned} E_z(z) &= \int_0^{2\pi} \frac{\lambda_0 a d\phi \cos\theta}{4\pi\epsilon_0(z^2 + a^2)}, \cos\theta = \frac{z}{(a^2 + z^2)^{\frac{1}{2}}} \\ &= \int_0^{2\pi} \frac{\lambda_0 a z}{(a^2 + z^2)^{\frac{3}{2}}} \frac{d\phi}{4\pi\epsilon_0} \\ &= \frac{\lambda_0 a z}{2\epsilon_0(a^2 + z^2)^{\frac{3}{2}}} \end{aligned}$$

Limit $|z| \rightarrow \infty$

$$\sqrt{a^2 + z^2} \rightarrow |z|$$

$$\Phi(z) \approx \frac{\lambda_0 a}{2\epsilon_0(a^2 + z^2)^{\frac{1}{2}}} \approx \frac{2\pi\lambda_0 a}{4\pi\epsilon_0|z|} \approx \frac{Q}{4\pi\epsilon_0|z|}$$

$Q = 2\pi\lambda_0 a$ (total charge on loop). $\Phi(z)$ looks like potential from point charge in far field.

$$E_z = \frac{\lambda_0 a z}{2\epsilon_0(a^2 + z^2)^{\frac{3}{2}}} \approx \frac{\lambda_0 a z}{2\epsilon_0|z|^3} = \begin{cases} \frac{Q}{4\pi\epsilon_0|z|^2} & z > 0 \\ \frac{-Q}{4\pi\epsilon_0|z|^2} & z < 0 \end{cases}$$

D

From (C), $\Phi = \frac{\lambda_0 r}{2\epsilon_0(r^2 + z^2)^{\frac{1}{2}}}$ for a ring of radius r . But now we have σ_0 , not λ_0 . How do we express λ_0 in terms of σ_0 ? Take a ring of width dr in the disk (see figure). Total charge = $\underbrace{(r)(2\pi)}_{\text{circumference}} (dr)\sigma_0$. Line charge

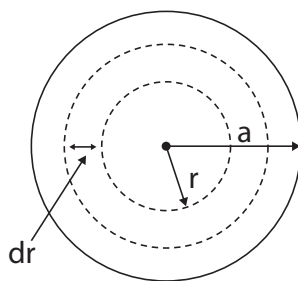


Figure 3: A ring of width dr in the disk (Image by MIT OpenCourseWare.)

density = $\lambda_0 = \frac{\text{total charge}}{\text{length}} = \sigma_0 dr$ So: $\lambda_0 = \sigma_0 dr$

$$\Phi = \frac{\sigma_0 r dr}{2\epsilon_0 (r^2 + z^2)^{\frac{1}{2}}}$$

$$\begin{aligned} \Phi_{\text{total}} &= \int_0^a \frac{\sigma_0 r dr}{2\epsilon_0 (r^2 + z^2)^{\frac{1}{2}}} = \frac{\sigma_0}{2\epsilon_0} \int_0^a \frac{r dr}{(r^2 + z^2)^{\frac{1}{2}}} \\ &= \frac{\sigma_0}{2\epsilon_0} \left[\sqrt{r^2 + z^2} \right]_{r=0}^{r=a} = \frac{\sigma_0}{2\epsilon_0} \left[\sqrt{a^2 + z^2} - |z| \right] \end{aligned}$$

$$\vec{E} = -\nabla\Phi_{\text{total}} = \frac{\sigma_0}{2\epsilon_0} z \left[\frac{1}{\sqrt{z^2}} - \frac{1}{\sqrt{a^2 + z^2}} \right] \vec{i}_z$$

E

As $z \rightarrow \infty$,

$$(a^2 + z^2)^{\frac{1}{2}} \rightarrow z + \frac{a^2}{2z}; \quad (a^2 + z^2)^{-\frac{1}{2}} \rightarrow \frac{1}{z} \left(1 - \frac{a^2}{2z^2} \right)$$

$$\Phi_{\text{total}} \rightarrow \frac{\pi a^2 \sigma_0}{4\epsilon_0 \pi z}$$

$$\vec{E} \rightarrow \frac{\pi a^2 \sigma_0}{4\pi \epsilon_0 z^2} \vec{i}_z$$

just like a point charge of $\sigma_0 \pi a^2$.

F

As $a \rightarrow \infty$, z in the $\sqrt{a^2 + z^2}$ can be neglected, so

$$\Phi_{\text{total}} \rightarrow \frac{\sigma_0}{2\epsilon_0} [a - |z|]$$

$$E_z \rightarrow \frac{\sigma_0 z}{2\epsilon_0} \left[\frac{1}{|z|} - 0 \right] = \begin{cases} \frac{\sigma_0}{2\epsilon_0} & z > 0 \\ \frac{-\sigma_0}{2\epsilon_0} & z < 0 \end{cases}$$

just like sheet charge.

Problem 2.3

A

By the divergence theorem:

i

$$\int_V \nabla \cdot (\nabla \times \vec{A}) dV = \oint_S (\nabla \times \vec{A}) \cdot d\vec{a}$$

where S encloses V . By Stokes' Theorem:

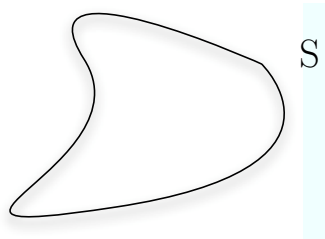


Figure 4: Closed surface S (Image by MIT OpenCourseWare.)

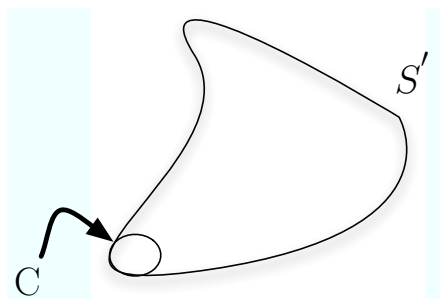


Figure 5: Open surface S' (Image by MIT OpenCourseWare.)

ii

$$\int_{S'} (\nabla \times \vec{A}) \cdot d\vec{a} = \oint_C \vec{A} \cdot d\vec{l}$$

Suppose S is as in figure 4

and S' is as in figure 5

i.e. S' is the same as S , except for the curve C , which makes S' slightly unclosed. Now consider limit as $C \rightarrow 0$ (Figure 6)

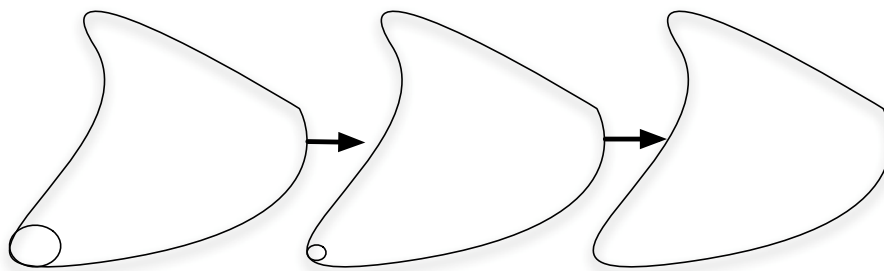


Figure 6: Limit as $C \rightarrow 0$ (Image by MIT OpenCourseWare.)

In limit $C \rightarrow 0, S' \rightarrow S$. If C is 0, then $\oint_C \vec{A} \cdot d\vec{l} = 0$. By equation (ii), $\int_S (\nabla \times \vec{A}) \cdot d\vec{a} = 0$. By equation (i), $\int_V \nabla \cdot (\nabla \times \vec{A}) dV = 0$. Since V can be any volume, argument of integral must be identically 0.

$$\nabla \cdot (\nabla \times \vec{A}) = 0$$

B

$$\vec{A} = A_x \hat{i}_x + A_y \hat{i}_y + A_z \hat{i}_z$$

$$\begin{aligned} \nabla \cdot (\nabla \times \vec{A}) &= \nabla \cdot \left[\left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) \hat{i}_x + \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) \hat{i}_y + \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \hat{i}_z \right] \\ &= \frac{\partial}{\partial x} \left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) + \frac{\partial}{\partial y} \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) + \frac{\partial}{\partial z} \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \\ &= \frac{\partial^2 A_z}{\partial x \partial y} - \frac{\partial^2 A_y}{\partial x \partial z} + \frac{\partial^2 A_x}{\partial y \partial z} - \frac{\partial^2 A_z}{\partial y \partial x} + \frac{\partial^2 A_y}{\partial z \partial x} - \frac{\partial^2 A_x}{\partial z \partial y} \\ &= 0 \text{ because of interchangeability of partial derivatives} \end{aligned}$$

In cylindrical coordinates

$$\begin{aligned} \vec{A} &= A_r \vec{i}_r + A_\phi \vec{i}_\phi + A_z \vec{i}_z \\ \nabla \times \vec{A} &= \vec{i}_r \left(\frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right) + \vec{i}_\phi \left(\frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right) + \vec{i}_z \frac{1}{r} \left[\frac{\partial(rA_\phi)}{\partial r} - \frac{\partial A_r}{\partial \phi} \right] \\ \nabla \cdot (\nabla \times \vec{A}) &= \frac{1}{r} \frac{\partial}{\partial r} \left(\frac{\partial A_z}{\partial \phi} - r \frac{\partial A_\phi}{\partial z} \right) + \frac{1}{r} \frac{\partial}{\partial \phi} \left(\frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right) + \frac{\partial}{\partial z} \left[\frac{1}{r} \frac{\partial(rA_\phi)}{\partial r} - \frac{1}{r} \frac{\partial A_r}{\partial \phi} \right] \\ &= \frac{1}{r} \frac{\partial^2 A_z}{\partial r \partial \phi} - \frac{r}{r} \frac{\partial^2 A_\phi}{\partial r \partial z} - \frac{1}{r} \frac{\partial A_\phi}{\partial z} + \frac{1}{r} \frac{\partial^2 A_r}{\partial \phi \partial z} - \frac{1}{r} \frac{\partial^2 A_z}{\partial r \partial \phi} + \frac{\partial^2 A_\phi}{\partial r \partial z} + \frac{1}{r} \frac{\partial A_\phi}{\partial z} - \frac{1}{r} \frac{\partial^2 A_r}{\partial \phi \partial z} \\ &= 0 \end{aligned}$$

Problem 2.4

A

$$Q = \int_{-\infty}^{\infty} \lambda(z) dz = \int_{-a}^a \frac{\lambda_0 z}{a} dz = \frac{\lambda_0 z^2}{2a} \Big|_{-a}^{+a} = 0$$

B

$$\Phi(\vec{r}) = \int_{V'} \frac{\rho(\vec{r}') dv'}{4\pi\epsilon_0 |\vec{r} - \vec{r}'|}$$

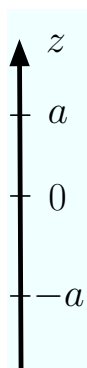


Figure 7: Axis showing extent of line charge $-a < z < a$ for Problem 2.4B (Image by MIT OpenCourseWare.)

$$\Phi(r = 0, z) = \int_{-a}^a \frac{\lambda_0 z' dz'}{4\pi\epsilon_0 |z - z'|a}$$

$$\Phi(r=0, z) = \frac{\lambda_0}{4\pi\epsilon_0 a} \int_{-a}^a \frac{z'}{z-z'} dz' = \left[z \ln \left(\frac{z+a}{z-a} \right) - 2a \right] \frac{\lambda_0}{4\pi\epsilon_0 a} \text{ for } z > a$$

$$\bar{E} = -\nabla\Phi$$

$$\begin{aligned} &= \frac{\lambda_0}{4\pi\epsilon_0 a} \frac{\partial}{\partial z} \left[z \ln \left(\frac{z+a}{z-a} \right) - 2a \right] \hat{i}_z \\ &= -\frac{\lambda_0}{4\pi\epsilon_0 a} \left[\ln \left(\frac{z+a}{z-a} \right) - \frac{2az}{(z+a)(z-a)} \right] \hat{i}_z \\ &= \frac{\lambda_0}{4\pi\epsilon_0 a} \left[\frac{2az}{(z+a)(z-a)} - \ln \left(\frac{z+a}{z-a} \right) \right] \hat{i}_z \end{aligned}$$

C

$$z \rightarrow \infty : \ln(1+x) = x - \frac{1}{2}x^2 + \frac{1}{3}x^3 \dots \quad x \ll 1$$

$$\Phi(z \rightarrow \infty) = \frac{\lambda_0}{4\pi\epsilon_0 a} \left[z \left(\frac{a}{z} - \frac{1}{2} \left(\frac{a}{z} \right)^2 + \frac{1}{3} \left(\frac{a}{z} \right)^3 - \left(\frac{-a}{z} - \frac{1}{2} \left(\frac{a}{z} \right)^2 - \frac{1}{3} \left(\frac{a}{z} \right)^3 \right) - 2a \right] \right]$$

$$= \frac{\lambda_0}{4\pi\epsilon_0 a} z \frac{2}{3} \frac{a^3}{z^3} = \frac{\frac{2}{3} a^2 \lambda_0}{4\pi\epsilon_0 z^2}$$

$$E_z(z \rightarrow \infty) = \frac{\lambda_0}{4\pi\epsilon_0 a} \left[\frac{2az}{z^2} \left(1 + \left(\frac{a}{z} \right)^2 \right) - \left(\frac{a}{z} - \frac{1}{2} \left(\frac{a}{z} \right)^2 + \frac{1}{3} \left(\frac{a}{z} \right)^3 + \frac{a}{z} + \frac{1}{2} \left(\frac{a}{z} \right)^2 + \frac{1}{3} \left(\frac{a}{z} \right)^3 \right) \right]$$

$$= \frac{\lambda_0}{4\pi\epsilon_0 a} \frac{4}{3} \left(\frac{a}{z} \right)^3 = \frac{\frac{4}{3} a^2 \lambda_0}{4\pi\epsilon_0 z^3}$$

It's a solution for dipole along z axis

D

$$p = \frac{2}{3} a^2 \lambda_0$$

Check: Zahn, pp. 139-140

$$\bar{p} = \int_{\text{all } q} \bar{r} dq \Rightarrow p_z = \int_{-a}^a z \lambda(z) dz = \int_{-a}^a \frac{\lambda_0 z^2}{a} dz = \frac{\lambda_0 z^3}{3a} \Big|_{-a}^a = \frac{2}{3} \lambda_0 a^2$$