

Generalized Polyhedral Approximations in Convex Optimization

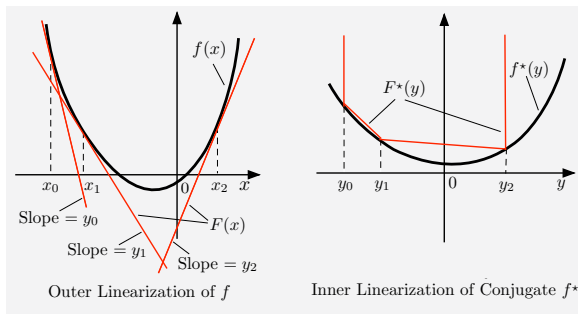
Dimitri P. Bertsekas

Department of Electrical Engineering and Computer Science
Massachusetts Institute of Technology

Lecture 21, 6.253 Class

Lecture Summary

- Outer/inner linearization and their duality.



- A unifying framework for polyhedral approximation methods.
- Includes classical methods:
 - Cutting plane/Outer linearization
 - Simplicial decomposition/Inner linearization
- Includes new methods, and new versions/extensions of old methods.

Vehicle for Unification

- Extended monotropic programming (EMP)

$$\min_{(x_1, \dots, x_m) \in S} \sum_{i=1}^m f_i(x_i)$$

where $f_i : \mathbb{R}^{n_i} \mapsto (-\infty, \infty]$ is a convex function and S is a subspace.

- The dual EMP is

$$\min_{(y_1, \dots, y_m) \in S^\perp} \sum_{i=1}^m f_i^*(y_i)$$

where f_i^* is the convex conjugate function of f_i .

- Algorithmic Ideas:

- Outer or inner linearization for some of the f_j
- Refinement of linearization using duality

- Features of outer or inner linearization use:

- They are combined in the same algorithm
- Their roles are reversed in the dual problem
- Become two (mathematically equivalent dual) faces of the same coin

Advantage over Classical Cutting Plane Methods

- The refinement process is much faster.
 - Reason: At each iteration we add multiple cutting planes (as many as one per component function f_i).
 - By contrast a single cutting plane is added in classical methods.
- The refinement process may be more convenient.
 - For example, when f_i is a scalar function, adding a cutting plane to the polyhedral approximation of f_i can be very simple.
 - By contrast, adding a cutting plane may require solving a complicated optimization process in classical methods.

References

- D. P. Bertsekas, "Extended Monotropic Programming and Duality," JOTA, 2008, Vol. 139, pp. 209-225.
- D. P. Bertsekas, "Convex Optimization Theory," 2009, www-based "living chapter" on algorithms.
- D. P. Bertsekas and H. Yu, "A Unifying Polyhedral Approximation Framework for Convex Optimization," Lab. for Information and Decision Systems Report LIDS-P-2820, MIT, September 2009.

Outline

- 1 Polyhedral Approximation
 - Outer and Inner Linearization
 - Cutting Plane and Simplicial Decomposition Methods
- 2 Extended Monotropic Programming
 - Duality Theory
 - General Approximation Algorithm
- 3 Special Cases
 - Cutting Plane Methods
 - Simplicial Decomposition for $\min_{x \in C} f(x)$

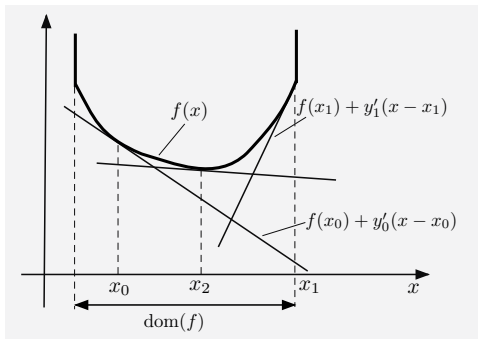
Outer Linearization - Epigraph Approximation by Halfspaces

- Given a convex function $f : \mathbb{R}^n \mapsto (-\infty, \infty]$.
- Approximation using subgradients:

$$\max \{f(x_0) + y'_0(x - x_0), \dots, f(x_k) + y'_k(x - x_k)\}$$

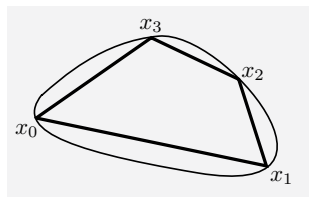
where

$$y_i \in \partial f(x_i), \quad i = 0, \dots, k$$

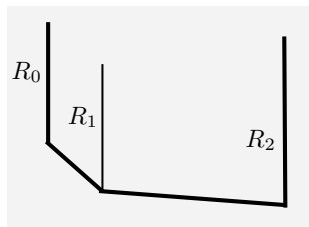


Convex Hulls

- Convex hull of a finite set of points x_i



- Convex hull of a union of a finite number of rays R_i

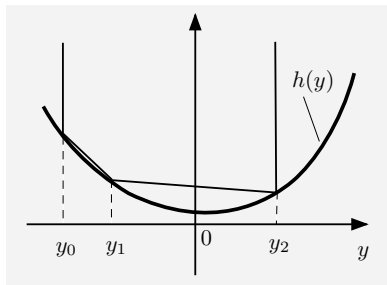


Inner Linearization - Epigraph Approximation by Convex Hulls

- Given a convex function $h : \mathbb{R}^n \mapsto (-\infty, \infty]$ and a finite set of points

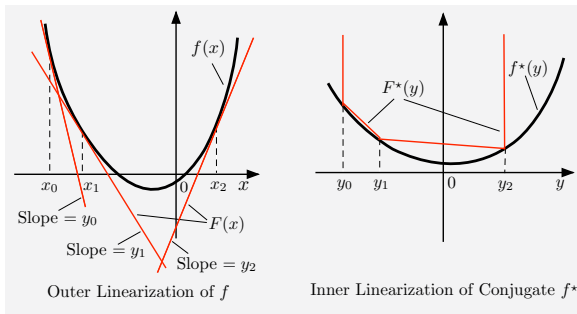
$$y_0, \dots, y_k \in \text{dom}(h)$$

- Epigraph approximation by convex hull of rays $\{(y_i, w) \mid w \geq h(y_i)\}$



Conjugacy of Outer/Inner Linearization

- Given a function $f : \mathbb{R}^n \mapsto (-\infty, \infty]$ and its conjugate f^* .
- The conjugate of an outer linearization of f is an inner linearization of f^* .



- Subgradients in outer lin. \iff Break points in inner lin.

Cutting Plane Method for $\min_{x \in C} f(x)$ (C polyhedral)

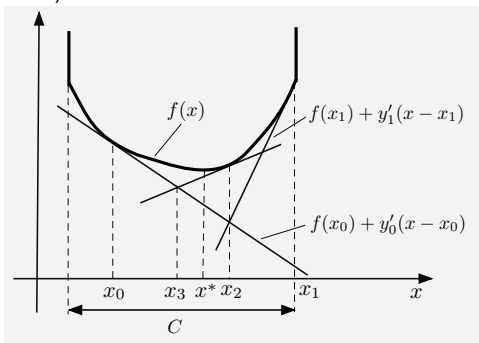
- Given $y_i \in \partial f(x_i)$ for $i = 0, \dots, k$, form

$$F_k(x) = \max \{f(x_0) + y'_0(x - x_0), \dots, f(x_k) + y'_k(x - x_k)\}$$

and let

$$x_{k+1} \in \arg \min_{x \in C} F_k(x)$$

- At each iteration **solves LP of large dimension** (which is simpler than the original problem).



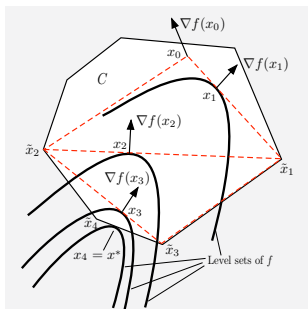
Simplicial Decomposition for $\min_{x \in C} f(x)$ (f smooth, C polyhedral)

- At the typical iteration we have x_k and $X_k = \{x_0, \tilde{x}_1, \dots, \tilde{x}_k\}$, where $\tilde{x}_1, \dots, \tilde{x}_k$ are extreme points of C .
- Solve LP of large dimension:** Generate

$$\tilde{x}_{k+1} \in \arg \min_{x \in C} \{\nabla f(x_k)'(x - x_k)\}$$

- Solve NLP of small dimension:** Set $X_{k+1} = \{\tilde{x}_{k+1}\} \cup X_k$, and generate X_{k+1} as

$$x_{k+1} \in \arg \min_{x \in \text{conv}(X_{k+1})} f(x)$$



- Finite convergence if C is a bounded polyhedron.

Comparison: Cutting Plane - Simplicial Decomposition

- **Cutting plane** aims to use LP with same dimension and smaller number of constraints.
- Most useful when problem has small dimension and:
 - There are many linear constraints, or
 - The cost function is nonlinear and linear versions of the problem are much simpler
- **Simplicial decomposition** aims to use NLP over a simplex of small dimension [i.e., $\text{conv}(X_k)$].
- Most useful when problem has large dimension and:
 - Cost is nonlinear, and
 - Solving linear versions of the (large-dimensional) problem is much simpler (possibly due to decomposition)
- The two methods appear very different, with unclear connection, despite the general conjugacy relation between outer and inner linearization.
- We will see that they are **special cases of two methods that are dual (and mathematically equivalent) to each other.**

Extended Monotropic Programming (EMP)

$$\min_{(x_1, \dots, x_m) \in S} \sum_{i=1}^m f_i(x_i)$$

where $f_i : \mathbb{R}^{n_i} \mapsto (-\infty, \infty]$ is a closed proper convex, S is subspace.

- **Monotropic programming** (Rockafellar, Minty), where f_i : scalar functions.
- **Single commodity network flow** (S : circulation subspace of a graph).
- **Block separable problems** with linear constraints.
- **Fenchel duality framework**: Let $m = 2$ and $S = \{(x, x) \mid x \in \mathbb{R}^n\}$. Then the problem

$$\min_{(x_1, x_2) \in S} f_1(x_1) + f_2(x_2)$$

can be written in the Fenchel format

$$\min_{x \in \mathbb{R}^n} f_1(x) + f_2(x)$$

- **Conic programs** (second order, semidefinite - special case of Fenchel).
- **Sum of functions** (e.g., machine learning): For $S = \{(x, \dots, x) \mid x \in \mathbb{R}^n\}$

$$\min_{x \in \mathbb{R}^n} \sum_{i=1}^m f_i(x)$$

Dual EMP

- Derivation: Introduce $z_i \in \mathfrak{R}^{n_i}$ and convert EMP to an equivalent form

$$\min_{(x_1, \dots, x_m) \in S} \sum_{i=1}^m f_i(x_i) \quad \equiv \quad \min_{\substack{z_i = x_i, i=1, \dots, m, \\ (x_1, \dots, x_m) \in S}} \sum_{i=1}^m f_i(z_i)$$

- Assign multiplier $y_i \in \mathfrak{R}^{n_i}$ to constraint $z_i = x_i$, and form the Lagrangian

$$L(x, z, y) = \sum_{i=1}^m f_i(z_i) + y_i'(x_i - z_i)$$

where $y = (y_1, \dots, y_m)$.

- The dual problem is to maximize the dual function

$$q(y) = \inf_{(x_1, \dots, x_m) \in S, z_i \in \mathfrak{R}^{n_i}} L(x, z, y)$$

- Exploiting the separability of $L(x, z, y)$ and changing sign to convert maximization to minimization, we obtain the dual EMP in symmetric form

$$\min_{(y_1, \dots, y_m) \in S^\perp} \sum_{i=1}^m f_i^*(y_i)$$

where f_i^* is the convex conjugate function of f_i .

Optimality Conditions

- There are powerful conditions for strong duality $q^* = f^*$ (generalizing classical monotropic programming results):
 - **Vector Sum Condition for Strong Duality:** Assume that for all feasible x , the set

$$S^\perp + \partial_\epsilon(f_1 + \dots + f_m)(x)$$

is closed for all $\epsilon > 0$. Then $q^* = f^*$.

- **Special Case:** Assume each f_i is finite, or is polyhedral, or is essentially one-dimensional, or is domain one-dimensional. Then $q^* = f^*$.
 - By considering the dual EMP, "finite" may be replaced by "co-finite" in the above statement.
- **Optimality conditions**, assuming $-\infty < q^* = f^* < \infty$:
 - (x^*, y^*) is an optimal primal and dual solution pair if and only if

$$x^* \in S, \quad y^* \in S^\perp, \quad y_i^* \in \partial f_i(x_i^*), \quad i = 1, \dots, m$$

- Symmetric conditions involving the dual EMP:

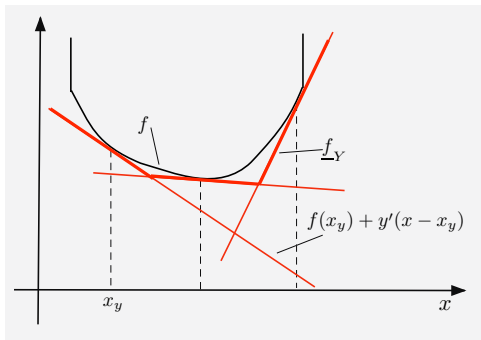
$$x^* \in S, \quad y^* \in S^\perp, \quad x_i^* \in \partial f_i^*(y_i^*), \quad i = 1, \dots, m$$

Outer Linearization of a Convex Function: Definition

- Let $f : \mathbb{R}^n \mapsto (-\infty, \infty]$ be closed proper convex.
- Given a **finite** set $Y \subset \text{dom}(f^*)$, we define the **outer linearization of f**

$$\underline{f}_Y(x) = \max_{y \in Y} \{f(x_y) + y'(x - x_y)\}$$

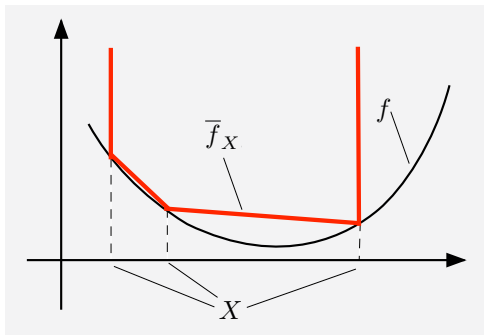
where x_y is such that $y \in \partial f(x_y)$.



Inner Linearization of a Convex Function: Definition

- Let $f : \mathbb{R}^n \mapsto (-\infty, \infty]$ be closed proper convex.
- Given a **finite** set $X \subset \text{dom}(f)$, we define the **inner linearization of f** as the function \bar{f}_X whose epigraph is the convex hull of the rays $\{(x, w) \mid w \geq f(x), x \in X\}$:

$$\bar{f}_X(z) = \begin{cases} \min_{\substack{\sum_{x \in X} \alpha_x x = z, \\ \sum_{x \in X} \alpha_x = 1, \alpha_x \geq 0, x \in X}} \sum_{x \in X} \alpha_x f(x) & \text{if } z \in \text{conv}(X) \\ \infty & \text{otherwise} \end{cases}$$



Polyhedral Approximation Algorithm

- Let $f_i : \mathfrak{R}^{n_i} \mapsto (-\infty, \infty]$ be closed proper convex, with conjugates f_i^* . Consider the EMP

$$\min_{(x_1, \dots, x_m) \in S} \sum_{i=1}^m f_i(x_i)$$

- Introduce a fixed partition of the index set:

$$\{1, \dots, m\} = I \cup \underline{I} \cup \bar{I}, \quad \underline{I}: \text{Outer indices}, \quad \bar{I}: \text{Inner indices}$$

- Typical Iteration:** We have finite subsets $Y_i \subset \text{dom}(f_i^*)$ for each $i \in \underline{I}$, and $X_i \subset \text{dom}(f_i)$ for each $i \in \bar{I}$.

Find primal-dual optimal pair $\hat{x} = (\hat{x}_1, \dots, \hat{x}_m)$, and $\hat{y} = (\hat{y}_1, \dots, \hat{y}_m)$ of the approximate EMP

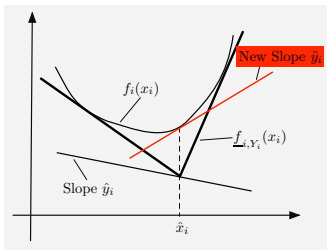
$$\min_{(x_1, \dots, x_m) \in S} \sum_{i \in \underline{I}} f_i(x_i) + \sum_{i \in \underline{I}} \underline{f}_{i, Y_i}(x_i) + \sum_{i \in \bar{I}} \bar{f}_{i, X_i}(x_i)$$

Enlarge Y_i and X_i by differentiation:

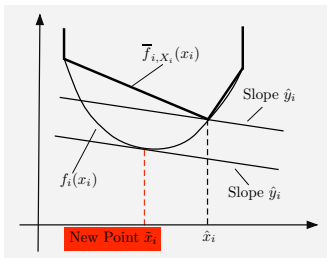
- For each $i \in \underline{I}$, add \tilde{y}_i to Y_i where $\tilde{y}_i \in \partial f_i(\hat{x}_i)$
- For each $i \in \bar{I}$, add \tilde{x}_i to X_i where $\tilde{x}_i \in \partial f_i^*(\hat{y}_i)$.

Enlargement Step for i th Component Function

- **Outer:** For each $i \in \underline{I}$, add \tilde{y}_i to Y_i where $\tilde{y}_i \in \partial f_i(\hat{x}_i)$.



- **Inner:** For each $i \in \bar{I}$, add \tilde{x}_i to X_i where $\tilde{x}_i \in \partial f_i^*(\hat{y}_i)$.



Mathematically Equivalent Dual Algorithm

- Instead of solving the primal approximate EMP

$$\min_{(x_1, \dots, x_m) \in S} \sum_{i \in I} f_i(x_i) + \sum_{i \in I} \underline{f}_{i, Y_i}(x_i) + \sum_{i \in \bar{I}} \bar{f}_{i, X_i}(x_i)$$

we may solve its dual

$$\min_{(y_1, \dots, y_m) \in S^\perp} \sum_{i \in I} f_i^*(y_i) + \sum_{i \in I} \underline{f}_{i, Y_i}^*(y_i) + \sum_{i \in \bar{I}} \bar{f}_{i, X_i}^*(x_i)$$

where \underline{f}_{i, Y_i}^* and \bar{f}_{i, X_i}^* are the conjugates of \underline{f}_{i, Y_i} and \bar{f}_{i, X_i} .

- Note that \underline{f}_{i, Y_i}^* is an inner linearization, and \bar{f}_{i, X_i}^* is an outer linearization (roles of inner/outer have been reversed).
- The choice of primal or dual is a matter of computational convenience, but **does not affect the primal-dual sequences produced**.

Comments on Polyhedral Approximation Algorithm

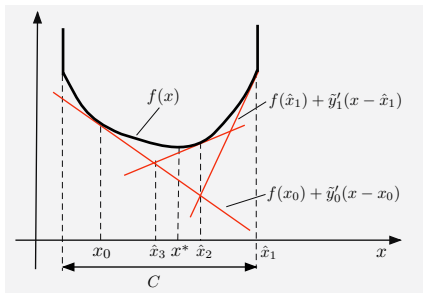
- In some cases we may use an algorithm that solves simultaneously the primal and the dual.
 - **Example:** Monotropic programming, where x_j is one-dimensional.
 - **Special case:** Convex separable network flow, where x_j is the one-dimensional flow of a directed arc of a graph, S is the circulation subspace of the graph.
- In other cases, it may be preferable to focus on solution of either the primal or the dual approximate EMP.
- After solving the primal, the refinement of the approximation (\tilde{y}_i for $i \in \underline{I}$, and \tilde{x}_i for $i \in \bar{I}$) may be found later by differentiation and/or some special procedure/optimization.
 - This may be easy, e.g., in the cutting plane method, or
 - This may be nontrivial, e.g., in the simplicial decomposition method.
- Subgradient duality [$y \in \partial f(x)$ iff $x \in \partial f^*(y)$] may be useful.

Cutting Plane Method for $\min_{x \in C} f(x)$

- EMP equivalent: $\min_{x_1=x_2} f(x_1) + \delta(x_2 \mid C)$, where $\delta(x_2 \mid C)$ is the indicator function of C .
- **Classical cutting plane algorithm:** Outer linearize f only, and solve the primal approximate EMP. It has the form

$$\min_{x \in C} \underline{f}_Y(x)$$

where Y is the set of subgradients of f obtained so far. If \hat{x} is the solution, add to Y a subgradient $\tilde{y} \in \partial f(\hat{x})$.



Simplicial Decomposition Method for $\min_{x \in C} f(x)$

- EMP equivalent: $\min_{x_1=x_2} f(x_1) + \delta(x_2 | C)$, where $\delta(x_2 | C)$ is the indicator function of C .
- **Generalized Simplicial Decomposition:** Inner linearize C only, and solve the primal approximate EMP. It has the form

$$\min_{x \in \bar{C}_X} f(x)$$

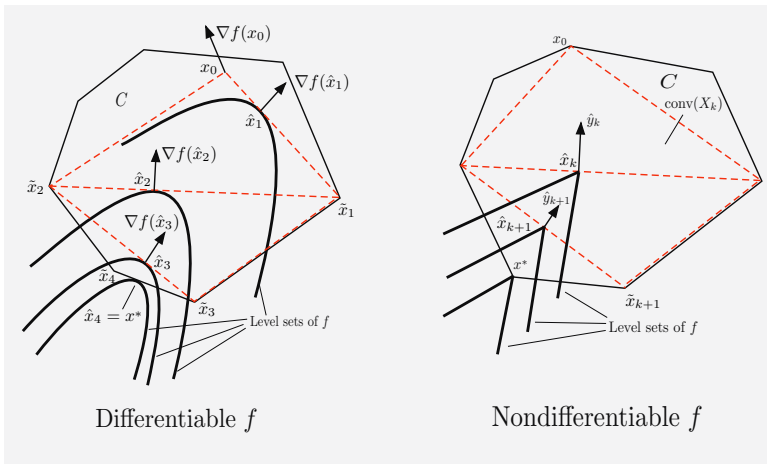
where \bar{C}_X is an inner approximation to C .

- Assume that \hat{x} is the solution of the approximate EMP.
 - Dual approximate EMP solutions:

$$\{(\hat{y}, -\hat{y}) \mid \hat{y} \in \partial f(\hat{x}), -\hat{y} \in (\text{normal cone of } \bar{C}_X \text{ at } \hat{x})\}$$

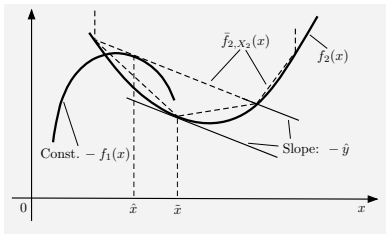
- In the **classical case** where f is differentiable, $\hat{y} = \nabla f(\hat{x})$.
- Add to X a point \tilde{x} such that $-\hat{y} \in \partial \delta(\tilde{x} | C)$, or

$$\tilde{x} \in \arg \min_{x \in C} \hat{y}'x$$

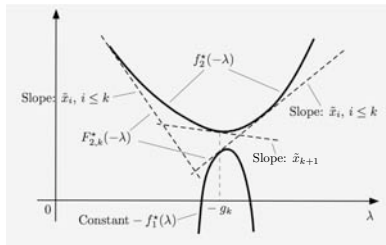
Illustration of Simplicial Decomposition for $\min_{x \in C} f(x)$ 

Dual Views for $\min_{x \in \mathbb{R}^n} \{f_1(x) + f_2(x)\}$

- Inner linearize f_2



- Dual view: Outer linearize f_2^*



Convergence - Polyhedral Case

- Assume that
 - All outer linearized functions f_j are finite polyhedral
 - All inner linearized functions f_j are co-finite polyhedral
 - The vectors \tilde{y}_j and \tilde{x}_j added to the polyhedral approximations are elements of the finite representations of the corresponding f_j
- **Finite convergence:** The algorithm terminates with an optimal primal-dual pair.
- **Proof sketch:** At each iteration two possibilities:
 - Either (\hat{x}, \hat{y}) is an optimal primal-dual pair for the original problem
 - Or the approximation of one of the $f_i, i \in \underline{I} \cup \bar{I}$, will be refined/improved
- By assumption there can be only a finite number of refinements. □

Convergence - Nonpolyhedral Case

- **Convergence, pure outer linearization** (\bar{I} : Empty). Assume that the sequence $\{\tilde{y}_i^k\}$ is bounded for every $i \in \underline{I}$. Then every limit point of $\{\hat{x}^k\}$ is primal optimal.
- **Proof sketch:** For all $k, m \leq k - 1$, and $x \in S$, we have

$$\sum_{i \notin \underline{I}} f_i(\hat{x}_i^k) + \sum_{i \in \underline{I}} (f_i(\hat{x}_i^m) + (\hat{x}_i^k - \hat{x}_i^m)' \tilde{y}_i^m) \leq \sum_{i \notin \underline{I}} f_i(\hat{x}_i^k) + \sum_{i \in \underline{I}} f_{-i, \gamma_i^{k-1}}(\hat{x}_i^k) \leq \sum_{i=1}^m f_i(x_i)$$

- Let $\{\hat{x}^k\}_{\mathcal{K}} \rightarrow \bar{x}$ and take limit as $m \rightarrow \infty, k \in \mathcal{K}, m \in \mathcal{K}, m < k$. □
- Exchanging roles of primal and dual, we obtain a convergence result for pure inner linearization case.
- **Convergence, pure inner linearization** (\underline{I} : Empty). Assume that the sequence $\{\tilde{x}_i^k\}$ is bounded for every $i \in \bar{I}$. Then every limit point of $\{\hat{y}^k\}$ is dual optimal.
- **General mixed case:** Convergence proof is more complicated (see the Bertsekas and Yu paper).

Concluding Remarks

- A unifying framework for polyhedral approximations based on EMP.
- Dual and symmetric roles for outer and inner approximations.
- There is option to solve the approximation using a primal method or a dual mathematical equivalent - whichever is more convenient/efficient.
- Several classical methods and some new methods are special cases.
- Proximal/bundle-like versions:
 - Convex proximal terms can be easily incorporated for stabilization and for improvement of rate of convergence.
 - Outer/inner approximations can be carried from one proximal iteration to the next.

MIT OpenCourseWare
<http://ocw.mit.edu>

6.253 Convex Analysis and Optimization

Spring 2010

For information about citing these materials or our Terms of Use, visit: <http://ocw.mit.edu/terms>.