6.854J / 18.415J Advanced Algorithms
Fall 2008

18.415/6.854 Advanced Algorithms	September 26, 2001
Lecture 5	
Lecturer: Michel X. Goemans	*Scribe: Dennis Quan*

1 The Ellipsoid Algorithm

Definition 1 *Let a be a point in $\mathbb{R}^n$ and A be an $n \times n$ positive definite matrix (i.e., A has positive eigenvalues). The ellipsoid $E(a, A)$ with center a is the set of points $\{x : (x-a)^T A^{-1}(x-a) \leq 1\}$. Therefore, the unit sphere is $E(0, I)$, where I is the identity matrix.*

An ellipsoid can be seen as the result of applying a linear transformation on a unit sphere. In other words, there is a linear transformation T that maps $E(a, A)$ to the unit sphere $E(0, I)$. It is known that for every positive definite matrix A, there is a $n \times n$ matrix B such that:

$$A = B^T B. \tag{1}$$

Therefore,

$$A^{-1} = B^{-1}(B^{-1})^T. \tag{2}$$

Using B, the transformation T can be seen as mapping points x to $(B^{-1})^T(x - a)$.

The Ellipsoid Algorithm solves the problem of finding an x subject to $Cx \leq d$ by looking at successively smaller ellipsoids E_k that contain the polyhedron $P := \{x : Cx \leq d\}$. Starting with an initial ellipsoid that contains P, we check to see if its center a is in P. If it is, we are done. If not, we look at the inequalities defining P, and choose one that is violated by a. This gives us a hyperplane through a such that P is completely on one side of this hyperplane. Then, we try to find an ellipsoid E_{k+1} that contains the *half-ellipsoid* defined by E_k and h.

The general step of finding the next ellipsoid E_{k+1} from E_k is given below. First we assume that E_k is a unit sphere centered at the origin, and the hyperplane h defines the half space $-e_1^T x \leq 0$ that contains P. Here, by e_i we mean the vector whose ith component is 1 and whose other components are 0. We will show later that it is easy to translate the general case to this case.

Therefore, we need an ellipsoid that contains

$$E(0, I) \cap \{x : -e_1^T x \leq 0\} \tag{3}$$

To find an ellipsoid that contains E_k, we showed last time that:

$$\underbrace{\left\{x : \left(\frac{n-1}{n}\right)^2 \left(x_1 - \frac{1}{n+1}\right)^2 + \frac{n^2-1}{n^2}\sum_{i=2}^{n} x_i^2 \leq 1\right\}}_{E_{k+1}} \subseteq E(0, I) \cap \{x : x_1 \geq 0\} \tag{4}$$

Therefore, we can define

$$E_{k+1} = E\left(\frac{1}{n+1}e_1, \frac{n^2}{n^2-1}(I - \frac{2}{n+1}e_1 e_1^T)\right). \tag{5}$$

($e_1 e_1^T$ = matrix with 1 in its top left cell, 0 elsewhere.) We also showed that

$$Vol(E_{k+1})/Vol(E_k) \leq \frac{n^2}{n^2-1}\frac{n}{n+1} \leq \exp\left(-\frac{1}{2n}\right) \tag{6}$$

For the more general case that we want to find an ellipsoid that contains $E(0,I) \cap \{x : d^T x \leq 0\}$ (we let $\|d\| = 1$; this can be done because the other side of the inequality is 0), it is easy to verify that we can take $E_{k+1} = E(-\frac{1}{n+1}d, F)$, where $F = \frac{n^2}{n^2-1}(I - \frac{2}{n+1}dd^T)$, and the ratio of the volumes is $\leq \exp\left(-\frac{1}{2n}\right)$.

Now we deal with the case where E_k is not the unit sphere. We take advantage of the fact that linear transformations preserve ratios of volumes.

$$\begin{array}{ccc} E_k & \stackrel{T}{\rightarrow} & E(0,1) \\ & & \downarrow \\ E_{k+1} & \stackrel{T^{-1}}{\leftarrow} & E' \end{array} \tag{7}$$

Let a_k be the center of E_k, and $c^T x \leq c^T a_k$ be the halfspace through a_k that contains P. Therefore, the half-ellipsoid that we are trying to contain is $E(a_k, A) \cap \{x : c^T x \leq c^T a_k\}$. Let's see what happens to this half-ellipsoid after the transformation T defined by $T(x) = (B^{-1})^T(x - a)$. This transformation transforms $E_k = E(a_k, A)$ to $E(0, I)$. Also,

$$\{x : c^T x \leq c^T a_k\} \stackrel{T}{\rightarrow} \{x : c^T(a_k + B^T y) \leq c^T a_k\} = \{x : c^T B^T y \leq 0\} = \{x : d^T x \leq 0\}, \tag{8}$$

where d is given by the following equation.

$$d = \frac{BC}{\sqrt{c^T B^T B c}} = \frac{BC}{\sqrt{c^T A c}} \tag{9}$$

Let $b = B^T d = \frac{Ac}{\sqrt{c^T Ac}}$. This implies:

$$E_{k+1} = E\left(a_k - \frac{1}{n+1}b, \frac{n^2}{n^2-1}B^T\left(I - \frac{2}{n+1}dd^T\right)B\right) \tag{10}$$

$$= E\left(a_k - \frac{1}{n+1}b, \frac{n^2}{n^2-1}\left(A - \frac{2}{n+1}bb^T\right)\right) \tag{11}$$

To summarize, here is the Ellipsoid Algorithm:

1. Start with $k = 0$, $E_0 = E(a_0, A_0) \supseteq P$, $P = \{x : Cx \leq d\}$.
2. While $a_k \notin P$ do:
   - Let $c^T x \leq d$ be an inequality that is valid for all $x \in P$ but $c^T a_k > d$.
   - Let $b = \frac{A_k c}{\sqrt{c^T A_k c}}$.
   - Let $a_{k+1} = a_k - \frac{1}{n+1}b$.
   - Let $A_{k+1} = \frac{n^2}{n^2-1}(A_k - \frac{2}{n+1}bb^T)$.

Claim 1 $\frac{Vol(E_{k+1})}{Vol(E_k)} \leq \exp\left(-\frac{1}{2n}\right)$

After k iterations, $Vol(E_k) \le Vol(E_0)\exp\left(-\frac{k}{2n}\right)$. If P is nonempty then the Ellipsoid Algorithm should find $x \in P$ in at most $2n \ln \frac{Vol(E_0)}{Vol(P)}$ steps.

What if P has volume 0 but is nonempty? In this case, we create an inflated polytope around P such that this new polytope is empty iff P is empty.

Theorem 2 *Let $P := \{x : Ax \le b\}$ and e be the vector of all ones. Assume that A has full column rank (certainly true if $Ax \le b$ contains the inequalities $-Ix \le 0$). Then P is nonempty iff $P' = \{x : Ax \le b + \frac{1}{2^L}e, -2^L \le x_j \le 2^L$ for all $j\}$ is nonempty. (L is the size of the LP P, as we defined in the previous lecture, but here we can remove the c_{max} term.)*

This theorem allows us to choose E_0 to be a ball centered at the origin containing the cube $\left[-2^L, 2^L\right]^n$. In this way, if there exists a $\hat{x}$ such that $A\hat{x} \le b$ then

$$\hat{x} + \left[-\frac{1}{2^{2L}}, \frac{1}{2^{2L}}\right]^n \in P' \tag{12}$$

Indeed, for a x in this little cube, we have $(Ax)_j \le (A\hat{x})_j + (\max_{i,j} a_{ij}) n \frac{1}{2^{2L}} \le b_j + \frac{1}{2^L}$.

The time for finding an x in P' is in $O(n \cdot nL)$, because the ratio of the volumes of $\left[-2^L, 2^L\right]^n$ to $\left[-\frac{1}{4^L}, \frac{1}{4^L}\right]^n$ is 8^{Ln}, and previously we showed that finding x in P was $O(n \ln \frac{Vol(E_0)}{Vol(P)})$. Thus, this process is polynomial in L.

Proof of Theorem 2: We first prove the forward implication. If $Ax \le b$ is nonempty then we can consider a vertex x in P (and there exists a vertex since A has full column rank). This implies that x will be defined by $A_S x = b_S$, where A_S is a submatrix of A (by problem 1 in Problem Set 1). Therefore, by a theorem from the previous lecture,

$$x = \left(\frac{p_1}{q}, \frac{p_2}{q}, \cdots, \frac{p_n}{q}\right) \tag{13}$$

with $|p_i| < 2^L$ and $1 \le q < 2^L$. Therefore,

$$|x_j| \le |p_j| < 2^L. \tag{14}$$

This proves the forward implication.

To show the converse, $\{x : Ax \le b\} = \emptyset$ implies, by Farkas' Lemma, there exists a y such that $y \ge 0$, $A^T y = 0$, and $b^T y = -1$. We can choose a vertex of $A^T y = 0$, $b^T y = -1$, $y \ge 0$. We can also phrase this as:

$$\begin{pmatrix} A^T \\ b^T \end{pmatrix} y = \begin{pmatrix} 0 \\ -1 \end{pmatrix}, y \ge 0 \tag{15}$$

By using Cramer's rule (like we did in the last lecture), we can bound the components of a basic feasible solution y in the following way:

$$y^T = \left(\frac{r_1}{s}, \cdots, \frac{r_m}{s}\right), \tag{16}$$

with $0 \le s, r_i \le \det_{max}\begin{pmatrix} A^T \\ b^T \end{pmatrix}$, where $\det_{max}(D)$ denotes the maximum subdeterminant in absolute value of any submatrix of D. By expanding the determinant along the last row, we see that $\det_{max}\begin{pmatrix} A^T \\ b^T \end{pmatrix} \le m b_{max} \det_{max}$ (where this last $\det_{max}$ refers to the matrix A). Using the fact that $2^L > 2^m 2^n \det_{max} b_{max}$, we get that $0 \le s, r_i < \frac{m}{2^m 2^n} 2^L \le \frac{m}{2^{m+1}} 2^L$.

Therefore,

$$\left(b + \frac{1}{2^L} e\right)^T y = \underbrace{b^T y}_{-1} + \frac{1}{2^L} e^T y = -1 + \frac{m^2}{2^{m+1}} < 0,$$

the last inequality following from the fact that $m^2 < 2^{m+1}$ for any integer $m \geq 1$. Therefore, by Farkas' Lemma again, this y shows that there exists no x where $Ax \leq b + \frac{1}{2^L} e$, i.e., P' is empty. □

There is also the problem of when x is found within P', x may not necessarily be in P. One solution is to round the coefficients of the inequalities to rational numbers and "repair" these inequalities to make x fit in P. This is called simultaneous Diophantine approximations, and will be discussed later on.

Here we solve this problem using another method: We give a general method for finding a feasible solution of a linear program, assuming that we have a procedure that checks whether or not the linear program is feasible.

Assume, we want to find a solution of $Ax \leq b$. The inequalities in this linear program can be written as $a_i^T x \leq b_i$ for $i = 1, \cdots, m$. We use the following algorithm:

1. $I \leftarrow \emptyset$.
2. For $i \leftarrow 1$ to m do
   - If the set of solutions of
     $$\left\{ \begin{array}{ll} a_j^T x \leq b_j & \forall j = i+1, \cdots, m \\ a_j^T x = b_j & \forall j \in I \cup \{i\} \end{array} \right\}$$
     is nonempty, then $I \leftarrow I \cup \{i\}$.
3. Finally, solve x in $a_i^T x = b_i$ for $i \in I$ with Gaussian elimination.

The correctness follows from the fact that if, in step 2, the system of inequalities has no solution then the inequality i can be discarded since it is redundant (removing it does not affect the set of solutions).

2 Applying the Ellipsoid Algorithm to Linear Programming

The algorithm we described today checks whether a set of inequalities are feasible, and if they are, finds a feasible solution. However, our initial goal was to find a feasible solution that minimizes a given linear objective function. Here, we give a general method for solving linear program, given a procedure that finds a feasible solution to a set of inequalities.

To solve the LP: $\min c^T x$ subject to $Ax = b$, $x \geq 0$:

Step 1: Check if $\{x : Ax = b, x \geq 0\}$ is nonempty; if it is empty, then the LP is infeasible; stop.

Step 2: Consider the dual LP: $\max b^T y$ subject to $A^T y \leq c$.
Check if there exists a y such that $A^T y \leq c$. If there does not exist such a y, then the original LP is unbounded by strong duality.

Step 3: If the dual LP is feasible, find a solution (x, y) where $Ax = b, x \geq 0, A^T y \leq c, c^T x = b^T y$.
By strong duality, $c^T x = b^T y$ will be the optimal solution.