

UNIT-5LAPLACE TRANSFORMS AND Z-TRANSFORMSLAPLACE TRANSFORMS:28/10

1, 2, 6, 10, 11, 12, 14, 20, 21, 23, 25, 26, 28, 33, 35, 38, 41, 42, 48, 50, 55, 58

- Laplace transform represents continuous time signals in terms of complex exponentials i.e. e^{-st} . It is used to analyze the signals or functions which are not absolutely integrable.
- More effectively continuous time signals can be analyzed using Laplace transform.
- Laplace transform provides broader characterization compared to Fourier Transform.

DEFINITION:

- To transform a time domain signal $x(t)$ to S -domain, multiply the signal by e^{-st} and then integrate from $-\infty$ to ∞ .
- The transformed signal is represented as $x(s)$ and transformation is denoted by letter $\mathcal{L}$.

Laplace transform is given as for continuous time signal $x(t)$

i.e.

$$x(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt \rightarrow (1)$$

where 's' is complex in nature and given as $s = \sigma + j\omega$.

→ real part / attenuation constant

→ imaginary / complex frequency

- If $x(t)$ is defined for $t \geq 0$ (i.e. $x(t)$ is causal) then

$$\mathcal{L}\{x(t)\} = x(s) = \int_0^{\infty} x(t) e^{-st} dt \rightarrow (2)$$

TYPES OF LAPLACE TRANSFORM:

- Bilateral or two sided Laplace transform: If the integration is taken from $-\infty$ to ∞ as shown in eq.(1) then it is called Bilateral LT.
 - Unilateral or one sided Laplace transform: If the integration is taken from 0 to ∞ as shown in eq.(2) then it is called Unilateral LT.
- Useful in analysis of networks and solving differential equations.

INVERSE LAPLACE TRANSFORM:

→ The s-domain signal $x(s)$ can be transformed to time domain signal $x(t)$ by using inverse Laplace transform and is defined as

$$\boxed{L^{-1}[x(s)] = x(t) = \frac{1}{2\pi j} \int_{\sigma-j\infty}^{\sigma+j\infty} x(s) e^{st} ds}$$

→ The signal $x(t)$ and $x(s)$ are called Laplace transform pair

$$x(t) \xrightleftharpoons[L^{-1}]{L} x(s)$$

RELATION BETWEEN FOURIER TRANSFORM AND LAPLACE TRANSFORM:

Fourier transform is given as

$$x(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt \rightarrow (1)$$

→ FT can be calculated only if $x(t)$ is absolutely integrable i.e.

$$\int_{-\infty}^{\infty} |x(t)| dt < \infty \rightarrow (2)$$

→ Laplace transform is written as

$$x(s) = \int_{-\infty}^{\infty} x(t) e^{-(\sigma+j\omega)t} dt \quad \text{putting } s = \sigma + j\omega$$

$$= \int_{-\infty}^{\infty} x(t) e^{-\sigma t} \cdot e^{-j\omega t} dt$$

$$= \left\{ \int_{-\infty}^{\infty} x(t) e^{-\sigma t} dt \right\} e^{-j\omega t} \rightarrow (3)$$

Comparing eq(3) with eq(1), Laplace transform of $x(t)$ is basically Fourier transform of $x(t) e^{-\sigma t}$.

→ If $\sigma = 0$, then above equation i.e. $s = j\omega$ the above eqn

$$x(s) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt = x(j\omega) \text{ when } s = j\omega.$$

→ It is basically Fourier transform on imaginary ($j\omega$) axis in s-plane.

CONVERGENCE / REGION OF CONVERGENCE (ROC):

→ From eqn $\left\{ \int_{-\infty}^{\infty} (x(t)e^{-\sigma t}) e^{-j\omega t} dt \right\}$ we know that Laplace transform is basically the Fourier transform of $x(t)e^{-\sigma t}$. If Fourier transform of $x(t)e^{-\sigma t}$ exists then Laplace transform of $x(t)$ exists.

→ $\int_{-\infty}^{\infty} |x(t)e^{-\sigma t}| dt < \infty$ must be absolutely integrable for Fourier transform to exist.

→ Laplace transform of $x(t)$ will exist, if above condition is satisfied.

→ The range of values of ' σ ' for which Laplace transform converges is called ROC or region of convergence.

(or)

→ The Laplace transform of a signal given by $\int_{-\infty}^{\infty} x(t)e^{-st} dt$. The values of ' s ' for which the integral $\int_{-\infty}^{\infty} x(t)e^{-st} dt$ converges is called ROC.

PROBLEMS:

(1) Calculate the Laplace transform and ROC for $x(t) = e^{-at}u(t)$ (Right sided causal sig)

Sol

$$x(t) = e^{-at}u(t) \text{ where } a > 0$$

$$= e^{-at} \text{ for } t \geq 0$$

$$L[x(t)] = X(s) = \int_{-\infty}^{\infty} x(t)e^{-st} dt = \int_{-\infty}^{\infty} e^{-at} \cdot u(t) e^{-st} dt$$

$$= \int_0^{\infty} e^{-at} e^{-st} dt = \int_0^{\infty} e^{-(s+a)t} dt$$

$$= \frac{1}{-(s+a)} \left[e^{-(s+a)t} \right]_0^{\infty} = \frac{-1}{s+a} [0 - 1]$$

$$= \frac{1}{s+a}$$

$$\text{ROC: } s > -a$$

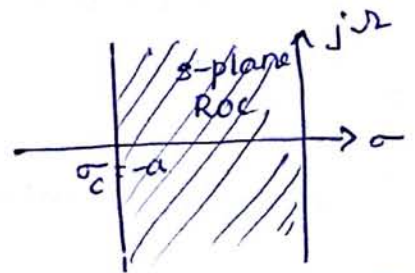
$$= - \left[\frac{e^{-(s+a)t}}{s+a} \right]_0^{\infty}$$

$$= \left\{ \lim_{t \rightarrow \infty} \left[\frac{e^{-(s+a)t}}{s+a} \right] - \lim_{t \rightarrow 0} \left[\frac{e^{-(s+a)t}}{s+a} \right] \right\}$$

$$x(s) = + \left[\frac{e^{-(s+a)\infty}}{-(s+a)} - \frac{e^{-(s+a)0}}{-(s+a)} \right]$$

$$s = j\omega + \sigma$$

$$L\{x(t)\} = \frac{e^{-k\infty} e^{-j\omega\infty}}{s+a} + \frac{1}{s+a}$$



$$\text{where } k = \sigma + a = \sigma - (-a)$$

when $\sigma > -a$, $k = \sigma - (-a) = \text{positive} \therefore e^{-k\infty} = e^{-\infty} = 0$

When $\sigma < -a$, $k = \sigma - (-a) = \text{Negative} \therefore e^{-k\infty} = e^{+\infty} = \infty$

$\therefore x(s)$ converges when $\sigma > -a$ and does not converge for $\sigma < -a$.

$\therefore$ When $\sigma > -a$, the $x(s)$ is given by

$$L\{x(t)\} = x(s) = \frac{-e^{-k\infty} e^{-j\omega\infty}}{s+a} + \frac{1}{s+a} = \frac{-0 \times e^{-j\omega\infty}}{s+a} + \frac{1}{s+a} = \frac{1}{s+a}$$

2,

Properties of L.T:

(1) Amplitude Scaling

If $L\{x(t)\} = X(s)$ then $L\{Ax(t)\} = AX(s)$

Proof:

$$X(s) = L\{x(t)\} = \int_{-\infty}^{\infty} x(t) \cdot e^{-st} dt$$

$$\begin{aligned} L\{Ax(t)\} &= \int_{-\infty}^{\infty} A \cdot x(t) e^{-st} dt = A \int_{-\infty}^{\infty} x(t) e^{-st} dt \\ &= AX(s) \end{aligned}$$

(2) Linearity:

If $L\{x_1(t)\} = X_1(s)$ and $L\{x_2(t)\} = X_2(s)$ then $L\{a_1 x_1(t) + a_2 x_2(t)\} = a_1 X_1(s) + a_2 X_2(s)$

Proof:

$$X_1(s) = L\{x_1(t)\} = \int_{-\infty}^{\infty} x_1(t) e^{-st} dt$$

$$X_2(s) = L\{x_2(t)\} = \int_{-\infty}^{\infty} x_2(t) e^{-st} dt$$

$$\begin{aligned} L\{a_1 x_1(t) + a_2 x_2(t)\} &= \int_{-\infty}^{\infty} [a_1 x_1(t) + a_2 x_2(t)] e^{-st} dt \\ &= a_1 \int_{-\infty}^{\infty} x_1(t) e^{-st} dt + a_2 \int_{-\infty}^{\infty} x_2(t) e^{-st} dt \\ &= a_1 X_1(s) + a_2 X_2(s) \end{aligned}$$

(3) Time differentiation:

If $L\{x(t)\} = X(s)$ then $L\left\{\frac{d}{dt} x(t)\right\} = sX(s) - x(0)$; where $x(0)$ is value of $x(t)$ at $t=0$

Proof:

$$X(s) = L\{x(t)\} = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

$$\therefore L\left\{\frac{d}{dt} x(t)\right\} = \int_{-\infty}^{\infty} \frac{dx(t)}{dt} e^{-st} dt = \int_{-\infty}^{\infty} e^{-st} \frac{dx(t)}{dt} dt$$

$$= [e^{-st} \cdot x(t)]_{-\infty}^{\infty} - \int_{-\infty}^{\infty} -s e^{-st} x(t) dt$$

$$= e^{-s\infty} x(\infty) - e^{-s0} x(0) + s \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

$$= s \int_{-\infty}^{\infty} x(t) e^{-st} dt - x(0) = sX(s) - x(0)$$

$$\left\{ \begin{aligned} \because \int u \frac{dv}{dt} &= uv - \int \left[\frac{du}{dt} v \right] \\ u &= e^{-st} \quad v = \frac{dx(t)}{dt} \end{aligned} \right.$$

(4) Time Integration:

If $L[x(t)] = X(s)$ then $L\left\{\int x(t) dt\right\} = \frac{X(s)}{s} + \frac{\left[\int x(t) dt\right]_{t=0}}{s}$

Proof

$$X(s) = L\{x(t)\} = \int_0^{\infty} x(t) e^{-st} dt$$

$$L\left\{\int x(t) dt\right\} = \int_0^{\infty} \left[\int x(t) dt\right] e^{-st} dt$$

$$= \left[\left[\int x(t) dt\right] \frac{e^{-st}}{-s} \right]_0^{\infty} - \int_0^{\infty} x(t) \cdot \frac{e^{-st}}{-s} dt$$

$$= \left[\int x(t) dt\right] \Big|_{t=\infty} \frac{e^{-\infty}}{-s} - \left[\int x(t) dt\right] \Big|_{t=0} \frac{e^0}{-s} + \frac{1}{s} \int_0^{\infty} x(t) e^{-st} dt$$

$$= \frac{1}{s} \left[\int x(t) dt\right] \Big|_{t=0} + \frac{1}{s} \int_0^{\infty} x(t) e^{-st} dt$$

$$= \frac{X(s)}{s} + \frac{\left[\int x(t) dt\right]_{t=0}}{s}$$

5) Frequency shifting:

If $L[x(t)] = X(s)$ then $L\{e^{\pm at} x(t)\} = X(s \mp a)$

Proof

$$X(s) = L\{x(t)\} = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

$$\therefore L\{e^{\pm at} x(t)\} = \int_{-\infty}^{\infty} e^{\pm at} x(t) \cdot e^{-st} dt$$

$$= \int_{-\infty}^{\infty} x(t) \cdot e^{-(s \mp a)t} dt$$

$$= X(s \mp a)$$

6) Time shifting

If $L\{x(t)\} = X(s)$ then $L\{x(t \pm a)\} = e^{\pm as} X(s)$

Proof:

$$x(s) = \mathcal{L}\{x(t)\} = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

$$\mathcal{L}\{x(t \pm a)\} = \int_{-\infty}^{\infty} x(t \pm a) e^{-st} dt = \int_{-\infty}^{\infty} x(\tau) e^{-s(\tau \mp a)} d\tau$$

put $t \pm a = \tau$: $t = \tau \mp a$ $dt = d\tau$

$$= \int_{-\infty}^{\infty} x(\tau) e^{-s\tau} \times e^{\pm as} d\tau = e^{\pm as} \int_{-\infty}^{\infty} x(\tau) e^{-s\tau} d\tau$$

$$= e^{\pm as} \int_{-\infty}^{\infty} x(t) e^{-st} dt = e^{\pm as} (x(s))$$

(7) Frequency differentiation:

$$\text{If } \mathcal{L}\{x(t)\} = x(s) \text{ then } \mathcal{L}\{t x(t)\} = -\frac{d}{ds} x(s)$$

Proof

$$x(s) = \mathcal{L}\{x(t)\} = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

$$\frac{d}{ds} x(s) = \frac{d}{ds} \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

$$= \int_{-\infty}^{\infty} x(t) \left(\frac{d}{ds} e^{-st} \right) dt = \int_{-\infty}^{\infty} x(t) (-t e^{-st}) dt$$

$$= \int_{-\infty}^{\infty} (-t x(t)) e^{-st} dt = \mathcal{L}\{-t x(t)\} = -\mathcal{L}\{t x(t)\}$$

$$\therefore \mathcal{L}\{t x(t)\} = -\frac{d}{ds} x(s).$$

(8) Frequency Integration:

$$\text{If } \mathcal{L}\{x(t)\} = x(s) \text{ then } \mathcal{L}\left\{\frac{1}{t} x(t)\right\} = \int_s^{\infty} x(s) ds.$$

Proof

$$x(s) = \mathcal{L}\{x(t)\} = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

On integrating above eqn w.r.to s b/w limits s to ∞

$$\int_s^{\infty} x(s) ds = \int_s^{\infty} \left[\int_{-\infty}^{\infty} x(t) e^{-st} dt \right] ds = \int_{-\infty}^{\infty} x(t) \left[\int_s^{\infty} e^{-st} ds \right] dt$$

$$= \int_{-\infty}^{\infty} x(t) \left[\frac{e^{-st}}{-t} \right]_s^{\infty} dt = \int_{-\infty}^{\infty} x(t) \left[\frac{e^{-\infty}}{-t} - \frac{e^{-st}}{-t} \right] dt$$

$$= \int_{-\infty}^{\infty} x(t) \left[0 + \frac{e^{-st}}{t} \right] dt = \int_{-\infty}^{\infty} \left[\frac{1}{t} x(t) \right] e^{-st} dt = \mathcal{L}\left\{\frac{1}{t} x(t)\right\}$$

9) Time Scaling:

If $L\{x(t)\} = X(s)$ then $L\{x(at)\} = \frac{1}{|a|} X\left(\frac{s}{a}\right)$

Proof

$$X(s) = L\{x(t)\} = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

$$\therefore L\{x(at)\} = \int_{-\infty}^{\infty} x(at) e^{-st} dt = \int_{-\infty}^{\infty} x(\tau) e^{-s\left(\frac{\tau}{a}\right)} \frac{d\tau}{a} \quad \left\{ \begin{array}{l} \text{put } at = \tau \\ \therefore dt = \frac{d\tau}{a} \end{array} \right.$$

$$= \frac{1}{a} \int_{-\infty}^{\infty} x(\tau) e^{-\left(\frac{s}{a}\right)\tau} d\tau$$

$$= \frac{1}{a} X\left(\frac{s}{a}\right)$$

The above transform is applicable for positive values of 'a'.

If 'a' happens to be negative

$$L\{x(at)\} = -\frac{1}{a} X\left(\frac{s}{a}\right)$$

In general, $L\{x(at)\} = \frac{1}{|a|} X\left(\frac{s}{a}\right)$.

(10) Periodicity:

If $x(t) = x(t+nT)$ and $x_1(t)$ be one period of $x(t)$ and $L\{x_1(t)\} = \int_0^T x_1(t) e^{-st} dt$

then $L\{x(t+nT)\} = \frac{1}{1-e^{-sT}} \int_0^T x_1(t) e^{-st} dt$

Proof

$$L\{x(t+nT)\} = \int_0^{\infty} x(t+nT) e^{-st} dt$$

$$= \int_0^T x_1(t) e^{-st} dt + \int_T^{2T} x_1(t-T) e^{-s(t-T)} dt + \int_{2T}^{3T} x_1(t-2T) e^{-s(t-2T)} dt + \dots$$

$$+ \dots + \int_{PT}^{(P+1)T} x_1(t-PT) e^{-s(t-PT)} dt + \dots$$

$$= \sum_{p=0}^{\infty} \int_{pT}^{(p+1)T} x_1(t-PT) e^{-s(t-PT)} dt$$

$$= \sum_{p=0}^{\infty} \int_0^T x_1(t) e^{-st} \cdot e^{-psT} dt = \int_0^T x_1(t) e^{-st} \left(\sum_{p=0}^{\infty} e^{-psT} \right) dt$$

$$= \int_0^T x_1(t) e^{-st} \left(\sum_{p=0}^{\infty} e^{-psT} \right) dt$$

$$= \int_0^T x_1(t) e^{-st} \left(\frac{1}{1-e^{-sT}} \right) dt = \frac{1}{1-e^{-sT}} \int_0^T x_1(t) e^{-st} dt$$

INVERSE LAPLACE TRANSFORM: (PARTIAL FRACTION EXPANSION)

The inverse Laplace transform by partial fraction method of all three cases.

Case i) when s-domain signal $x(s)$ has distinct poles

$$\text{Let } x(s) = \frac{k}{s(s+p_1)(s+p_2)}$$

By partial fraction

$$x(s) = \frac{k_1}{s} + \frac{k_2}{s+p_1} + \frac{k_3}{s+p_2}$$

The residues k_1, k_2, k_3 are given by

$$k_1 = x(s) \times s \Big|_{s=0}, \quad k_2 = x(s) \times (s+p_1) \Big|_{s=-p_1}$$

$$k_3 = x(s) \times (s+p_2) \Big|_{s=-p_2}$$

$$L^{-1}\{x(s)\} = L^{-1}\left\{\frac{k_1}{s} + \frac{k_2}{s+p_1} + \frac{k_3}{s+p_2}\right\}$$

$$x(t) = k_1 L^{-1}\left\{\frac{1}{s}\right\} + k_2 L^{-1}\left\{\frac{1}{s+p_1}\right\} + k_3 L^{-1}\left\{\frac{1}{s+p_2}\right\}$$

$$= k_1 u(t) + k_2 e^{-p_1 t} u(t) + k_3 e^{-p_2 t} u(t).$$

Case ii) when s-domain signal $x(s)$ has multiple poles

$$x(s) = \frac{k}{s(s+p_1)(s+p_2)^r}$$

$$x(s) = \frac{k_1}{s} + \frac{k_2}{s+p_1} + \frac{k_3}{(s+p_2)^r} + \frac{k_4}{s+p_2}$$

The residues k_1, k_2, k_3, k_4 are given by

$$k_1 = x(s) \times s \Big|_{s=0}, \quad k_2 = x(s) \times (s+p_1) \Big|_{s=-p_1}$$

$$k_3 = x(s) \times (s+p_2)^r \Big|_{s=-p_2}, \quad k_4 = \frac{d}{ds} [x(s) \times (s+p_2)^r] \Big|_{s=-p_2}$$

$$L^{-1}\{x(s)\} = L^{-1}\left\{\frac{k_1}{s} + \frac{k_2}{s+p_1} + \frac{k_3}{(s+p_2)^r} + \frac{k_4}{s+p_2}\right\}$$

$$= k_1 u(t) + k_2 e^{-p_1 t} u(t) + k_3 t e^{-p_2 t} u(t) + k_4 e^{-p_2 t} u(t)$$

In general

$$X(s) = \frac{k}{s(s+p_1)(s+p_2)^q} \text{ then}$$

$$X(s) = \frac{k_1}{s} + \frac{k_2}{s+p_1} + \frac{k_3}{(s+p_2)^q} + \frac{k_4}{(s+p_2)^{q-1}} + \dots + \frac{k_{(q-1)2}}{s+p_2}$$

$$k_{r2} = \frac{1}{r!} \frac{d^r}{ds^r} \left[X(s) (s+p_2)^q \right]; r=1, 2, \dots, q-1.$$

Case iii) When s-domain signal $X(s)$ has complex conjugate poles

$$\text{Let } X(s) = \frac{k}{(s+p_1)(s^2+bs+c)}$$

$$X(s) = \frac{k_1}{s+p_1} + \frac{k_2 s + k_3}{s^2+bs+c}$$

$$k_1 = X(s) \times (s+p_1)_{s=-p_1}$$

$$X(s) = \frac{k_1}{s+p_1} + \frac{k_2 s + k_3}{s^2 + 2 \times \frac{b}{2} \cdot s + \left(\frac{b}{2}\right)^2 + c - \left(\frac{b}{2}\right)^2}$$

Arranging s^2+bs
in $(x+y)^2$.

$$= \frac{k_1}{s+p_1} + \frac{k_2 s + k_3}{\left(s + \frac{b}{2}\right)^2 + \left(c - \frac{b^2}{4}\right)}$$

$$\text{put } \frac{b}{2} = a, \quad c - \frac{b^2}{4} = \omega_0^2$$

$$X(s) = \frac{k_1}{s+p_1} + k_2 \cdot \frac{s+a + \frac{k_3}{k_2} - a}{(s+a)^2 + \omega_0^2}$$

$$= \frac{k_1}{s+p_1} + k_2 \cdot \frac{s+a+k_4}{(s+a)^2 + \omega_0^2}$$

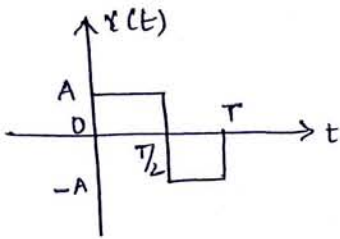
($\because$ put $\frac{k_3}{k_2} - a = k_4$)

$$\therefore X(s) = \frac{k_1}{s+p_1} + k_2 \cdot \frac{s+a}{(s+a)^2 + \omega_0^2} + k_5 \frac{\omega_0}{(s+a)^2 + \omega_0^2} \quad \left(\frac{k_2 k_4}{\omega_0} = k_5 \right)$$

$$x(t) = k_1 e^{-p_1 t} u(t) + k_2 e^{-at} \cos \omega_0 t u(t) + k_5 e^{-at} \sin \omega_0 t u(t).$$

LAPLACE TRANSFORM OF CERTAIN SIGNALS USING WAVEFORM SYNTHESIS

(a)



proof

$$x(t) = A \text{ for } 0 < t < T/2$$

$$= -A \text{ for } T/2 < t < T$$

$$L\{x(t)\} = X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt = \int_0^T x(t) e^{-st} dt$$

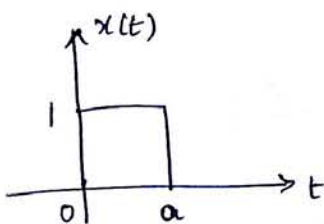
$$= \int_0^{T/2} A e^{-st} dt + \int_{T/2}^T (-A) e^{-st} dt = \left[\frac{A e^{-st}}{-s} \right]_0^{T/2} + \left[\frac{-A e^{-st}}{-s} \right]_{T/2}^T$$

$$= \left[\frac{A e^{-sT/2}}{-s} - \frac{A e^0}{-s} \right] + \left[\frac{A e^{-sT}}{s} - \frac{A e^{-sT/2}}{s} \right]$$

$$= -\frac{A e^{-sT/2}}{s} + \frac{A}{s} + \frac{A e^{-sT}}{s} - \frac{A e^{-sT/2}}{s}$$

$$= \frac{A}{s} \left[1 - e^{-sT/2} \right]$$

(b)



proof

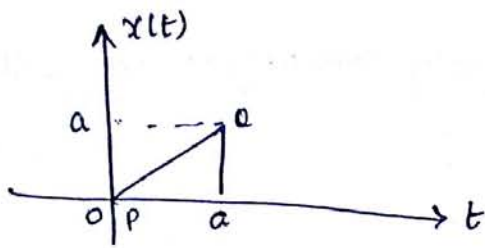
$$x(t) = 1 \text{ for } 0 < t < a$$

$$= 0 \text{ for } t > a$$

$$L\{x(t)\} = X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt = \int_0^a 1 \times e^{-st} dt = \int_0^a e^{-st} dt$$

$$= \left[\frac{e^{-st}}{-s} \right]_0^a = \frac{e^{-as}}{-s} - \frac{e^0}{-s} = -\frac{e^{-as}}{s} + \frac{1}{s} = \frac{1}{s} (1 - e^{-as})$$

(C)



Consider the eqn of straight line $\frac{y-y_1}{y_2-y_1} = \frac{x-x_1}{x_2-x_1}$

Here $y = x(t)$, $x = t$

Consider points P and Q as shown in figure

$$P = [0, 0], \quad Q = [a, a]$$

$$t_1, x_1(t) \quad t_2, x_2(t)$$

$$\therefore \frac{x(t)-0}{0-a} = \frac{t-0}{0-a} \Rightarrow x(t) = t$$

$$\therefore x(t) = t \quad \text{for } t = 0 \text{ to } a$$

$$= 0 \quad \text{for } t > a$$

$$\mathcal{L}\{x(t)\} = x(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt = \int_0^a e^{-st} \cdot t dt$$

$$= \left[t \times \frac{e^{-st}}{-s} - \int 1 \cdot \frac{e^{-st}}{-s} dt \right]_0^a$$

$$= \left[-\frac{te^{-st}}{s} - \frac{e^{-st}}{s^2} \right]_0^a$$

$$= \left[-\frac{ae^{-sa}}{s} - \frac{e^{-sa}}{s^2} + 0 + \frac{e^0}{s^2} \right]$$

$$= \frac{1}{s^2} - \frac{e^{-as}}{s^2} - \frac{ae^{-as}}{s}$$

$$= \frac{1}{s^2} \left[1 - e^{-as}(1+as) \right]$$

Problems on Laplace transforms:

(1) Determine the Laplace transform of continuous time signals and their ROC

(a) $x(t) = A u(t)$

$$x(t) = A \text{ for } t \geq 0 \text{ bcoz } u(t) = 1 \text{ for } t \geq 0 \\ = 0 \text{ for } t < 0$$

Laplace transform

$$L\{x(t)\} = X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt = \int_0^{\infty} A \cdot e^{-st} dt = A \left[\frac{e^{-st}}{-s} \right]_0^{\infty}$$

$$= A \left[\frac{e^{-(\sigma + j\omega)t}}{-s} \right]_0^{\infty}$$

$$= A \left[\frac{e^{-(\sigma + j\omega) \times \infty}}{-s} + \frac{e^0}{s} \right] = A \left[\frac{e^{-\sigma \times \infty} \cdot e^{-j\omega \times \infty}}{-s} + \frac{e^0}{s} \right]$$

$$\text{when } \sigma > 0 ; e^{-\sigma \times \infty} = e^{-\infty} = e^{-\infty} = 0$$

$$\text{when } \sigma < 0 ; e^{-\sigma \times \infty} = e^{\infty} = \infty$$

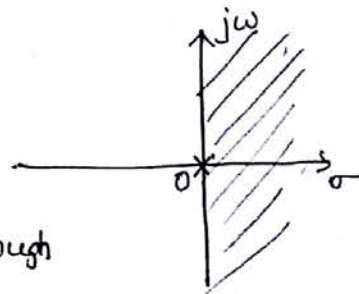
$\therefore$ we can say that $X(s)$ converges when $\sigma > 0$

When $\sigma > 0$, the $X(s)$ is given by

$$X(s) = A \left[\frac{0 \times e^{-j\omega \times \infty}}{-s} + \frac{1}{s} \right] = \frac{A}{s}$$

$\therefore L\{A u(t)\} = \frac{A}{s}$; with ROC as all point is s-plane to the right of line passing through $\sigma = 0$

(or ROC is right half of s-plane).



(2) $x(t) = t u(t)$

Sol $x(t) = t \begin{cases} u(t) = 1 \text{ for } t \geq 0 \\ = 0 \text{ otherwise} \end{cases}$

$$\mathcal{L}\{x(t)\} = X(s) = \int_0^{\infty} x(t) e^{-st} dt$$

$$\int u v = u \int v - \int [du] v$$

$$= \int_0^{\infty} t \cdot e^{-st} dt = \left[\frac{e^{-st}}{-s} \right]_0^{\infty} - \int \left[\frac{e^{-st}}{-s} \right]_0^{\infty}$$

$$= \left[\frac{e^{-st}}{-s} \right]_0^{\infty} - \left[\frac{e^{-st}}{s^2} \right]_0^{\infty}$$

$$= \left[\frac{e^{-(\sigma+j\omega)t}}{-s} \right]_0^{\infty} - \left[\frac{e^{-(\sigma+j\omega)t}}{s^2} \right]_0^{\infty}$$

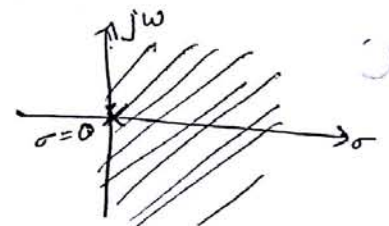
$$= \left[\infty \times \frac{e^{-(\sigma+j\omega)\infty}}{-s} - 0 - \frac{e^{-(\sigma+j\omega)\infty}}{s^2} + \frac{e^0}{s^2} \right]$$

$$= \left[\infty \times \frac{e^{-\sigma \times \infty} \cdot e^{-j\omega \times \infty}}{-s} - \frac{e^{-\sigma \times \infty} \cdot e^{-j\omega \times \infty}}{s^2} + \frac{1}{s^2} \right]$$

when $\sigma > 0$, positive i.e. $e^{-\sigma \times \infty} = e^{-\sigma \infty} = 0$

when $\sigma < 0$, negative i.e. $e^{-\sigma \times \infty} = e^{\sigma \infty} = \infty$

It converges when $\sigma > 0$



$$= \left[\infty \times \frac{0 \times e^{-j\omega \times \infty}}{-s} - \frac{0 \times e^{-j\omega \times \infty}}{s^2} + \frac{1}{s^2} \right] = \frac{1}{s^2}$$

$\therefore$ ROC is right half of s-plane.

3) Given that $x(t) = e^{-3t} u(t)$:

Sol $x(t) = e^{-3t}$ for $t \geq 0$

$$\mathcal{L}\{x(t)\} = X(s) = \int_{-\infty}^{\infty} x(t) \cdot e^{-st} dt$$

$$= \int_0^{\infty} x(t) \cdot e^{-st} dt = \int_0^{\infty} e^{-3t} \cdot e^{-st} dt = \int_0^{\infty} e^{-(s+3)t} dt.$$

$$= \left[\frac{e^{-(s+3)t}}{-(s+3)} \right]_0^{\infty}$$

$$= \left[\frac{e^{-(s+3)\infty}}{-(s+3)} + \frac{e^{-(s+3) \cdot 0}}{s+3} \right] \Rightarrow \frac{e^{-(\sigma+j\omega+3)\infty}}{-(s+3)} + \frac{1}{s+3}$$

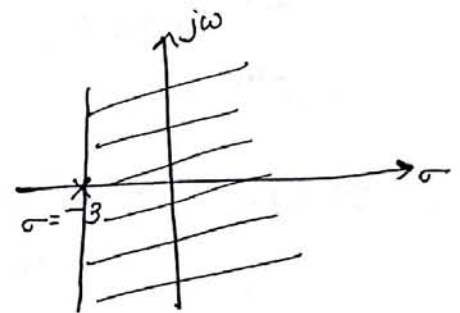
$$= \left[\frac{e^{-(\sigma+j\omega)\infty} \cdot e^{-3\infty}}{-(s+3)} + \frac{1}{s+3} \right]$$

$$\sigma+3 = \sigma - (-3)$$

if $\sigma > -3 = \text{positive}$ $\therefore e^{-k \times \infty} = e^{-k\infty} = 0$

if $\sigma < -3 = \text{negative}$ $\therefore e^{-k \times \infty} = e^{k\infty} = \infty$

$\therefore$ It converges at $\sigma > -3$.



$$x(s) = \left[\frac{0 \times e^{-j\omega \times \infty}}{-(s+3)} + \frac{1}{s+3} \right] = \frac{1}{s+3}$$

$\mathcal{L}\{e^{-3t} u(t)\} = \frac{1}{s+3}$; with Roc as all pts in s-plane to right of line passing through $\sigma = -3$

(4) $x(t) = e^{-3t} u(-t)$

$x(t) = e^{-3t}$ for $t \leq 0$

$\mathcal{L}\{x(t)\} = x(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt = \int_{-\infty}^0 e^{-3t} e^{-st} dt$

$$= \int_{-\infty}^0 e^{-(s+3)t} dt$$

$$= \left[\frac{e^{-(s+3)t}}{-(s+3)} \right]_{-\infty}^0 = \frac{e^0}{-(s+3)} + \frac{e^{+(s+3)\infty}}{-(s+3)}$$

$$= \frac{-1}{s+3} + \frac{e^{+(\sigma+j\omega+3)\infty}}{s+3}$$

$$= \frac{-1}{s+3} + \frac{e^{+(\sigma+3) \times \infty} \cdot e^{-j\omega \times \infty}}{s+3}$$

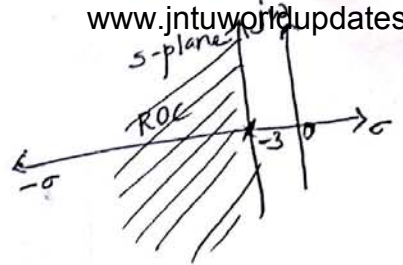
$$k = \sigma + 3 = \sigma - (-3)$$

when $\sigma > -3$; ~~positive~~ positive $e^{+(\sigma+3) \times \infty} = \infty$

when $\sigma < -3$; negative $e^{-k\infty} = e^{k\infty} = 0$

$$\therefore \text{Roc it converges when } \sigma < -3 \Rightarrow \frac{-1}{s+3} + \frac{0 \times e^{-j\omega \times \infty}}{s+3}$$

$$L\{x(t)\} = L\{e^{-3t} u(-t)\} = \frac{-1}{s+3} \left\{ \text{Roc as all pts in plane to the left passing through } \sigma = -3 \right\}$$



$$(5) \quad x(t) = e^{-4t}$$

$$= e^{-4t} \text{ for } t \geq 0$$

$$= e^{+4t} \text{ for } t \leq 0$$

$$L\{x(t)\} = X(s) = \int_{-\infty}^{\infty} x(t) \cdot e^{-st} dt = \int_{-\infty}^0 e^{4t} \cdot e^{-st} dt + \int_0^{\infty} e^{-4t} \cdot e^{-st} dt$$

$$= \int_{-\infty}^0 e^{-(s-4)t} dt + \int_0^{\infty} e^{-(s+4)t} dt$$

$$= \left[\frac{e^{-(s-4)t}}{-(s-4)} \right]_{-\infty}^0 + \left[\frac{e^{-(s+4)t}}{-(s+4)} \right]_0^{\infty}$$

$$= \left[\frac{1}{-(s-4)} + \frac{e^{+(s-4) \times \infty}}{s-4} + \frac{e^{-(s+4) \times \infty}}{s+4} + \frac{1}{s+4} \right]$$

$$= \left[\frac{-1}{s-4} + \frac{e^{(\sigma+j\omega-4) \times \infty}}{s-4} - \frac{e^{-(\sigma+j\omega+4) \times \infty}}{s+4} + \frac{1}{s+4} \right]$$

$$= \left[\frac{-1}{s-4} + \frac{e^{(\sigma-4) \times \infty} \cdot e^{j\omega \times \infty}}{s-4} - \frac{e^{-(\sigma+4) \times \infty} \cdot e^{-j\omega \times \infty}}{s+4} + \frac{1}{s+4} \right]$$

$$\sigma - 4 \Rightarrow \sigma < 4$$

when $\sigma > 4$ positive $e^{k \times \infty} = \infty$

when $\sigma < 4$ negative $e^{-k\infty} = 0$

It converges when $\sigma < 4$

$$\sigma + 4 \rightarrow \sigma > -4$$

when $\sigma > 4$ positive $e^{-k\infty} = 0$

when $\sigma < -4$ negative $e^{k\infty} = \infty$

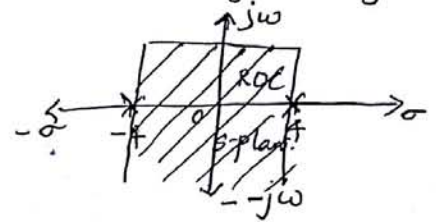
It converges when $\sigma > -4$

When σ lies between -4 and $+4$, the $x(s)$ is given by

$$x(s) = \left[\frac{-1}{s-4} + \frac{e^{(\sigma-4)\infty} e^{j\omega\infty}}{s-4} - \frac{e^{-(\sigma+4)\infty} e^{-j\omega\infty}}{s+4} + \frac{1}{s+4} \right]$$

$$= \frac{-1}{s-4} + \frac{1}{s+4} \Rightarrow \frac{-s-4+s-4}{s^2-16} = \frac{-8}{s^2-16}$$

with ROC as all points in s -plane in between the lines passing through $\sigma = -4$ and $\sigma = 4$.



⑥ Determine the Laplace transform of following signals.

$$x(t) = \sin \omega_0 t u(t)$$

Sol $x(t) = \sin \omega_0 t$ for $t \geq 0$

$$\mathcal{L}\{x(t)\} = X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

$$= \int_{0}^{\infty} \sin \omega_0 t \cdot e^{-st} dt$$

$$= \int_{0}^{\infty} \frac{e^{j\omega_0 t} - e^{-j\omega_0 t}}{2j} \cdot e^{-st} dt$$

$$\therefore \sin \theta = \frac{e^{j\theta} - e^{-j\theta}}{2j}$$

$$= \frac{1}{2j} \left[\int_{0}^{\infty} e^{-(s-j\omega_0)t} dt - \int_{0}^{\infty} e^{-(s+j\omega_0)t} dt \right]$$

$$= \frac{1}{2j} \left[\left[\frac{e^{-(s-j\omega_0)t}}{-(s-j\omega_0)} \right]_0^{\infty} - \left[\frac{e^{-(s+j\omega_0)t}}{-(s+j\omega_0)} \right]_0^{\infty} \right]$$

$$= \frac{1}{2j} \left[\frac{e^{-\infty}}{-(s-j\omega_0)} + \frac{e^0}{s-j\omega_0} + \frac{e^{-\infty}}{s+j\omega_0} - \frac{e^0}{s+j\omega_0} \right]$$

$$= \frac{1}{2j} \left[\frac{1}{s-j\omega_0} - \frac{1}{s+j\omega_0} \right] = \frac{1}{2j} \left[\frac{s+j\omega_0 - s+j\omega_0}{s^2 - j^2 \omega_0^2} \right] = \frac{2j\omega_0}{2j(s^2 + \omega_0^2)}$$

$$= \frac{\omega_0}{s^2 + \omega_0^2}$$

(7) $x(t) = \cos \omega_0 t \, u(t)$

Sol
 $x(t) = \cos \omega_0 t \quad ; t \geq 0$

$$L\{x(t)\} = X(s) = \int_0^{\infty} x(t) \cdot e^{-st} dt = \int_0^{\infty} \frac{e^{j\omega_0 t} + e^{-j\omega_0 t}}{2} \cdot e^{-st} dt$$

$$= \frac{1}{2} \int_0^{\infty} [e^{-(s-j\omega_0)t} + e^{-(s+j\omega_0)t}] dt$$

$$= \frac{1}{2} \left[\frac{e^{-(s-j\omega_0)t}}{-(s-j\omega_0)} + \frac{e^{-(s+j\omega_0)t}}{-(s+j\omega_0)} \right]_0^{\infty}$$

$$= \frac{1}{2} \left[\frac{e^{-\infty}}{-(s-j\omega_0)} + \frac{e^0}{s-j\omega_0} - \frac{e^{-\infty}}{s+j\omega_0} + \frac{e^0}{s+j\omega_0} \right]$$

$$= \frac{1}{2} \left[\frac{1}{s-j\omega_0} + \frac{1}{s+j\omega_0} \right] = \frac{1}{2} \left[\frac{s+j\omega_0 + s-j\omega_0}{s^2 - j\omega_0^2} \right] = \frac{1}{2} \cdot \frac{2s}{s^2 + \omega_0^2}$$

$$L\{\cos \omega_0 t \, u(t)\} = \frac{s}{s^2 + \omega_0^2}$$

8) $x(t) = \cosh \omega_0 t \, u(t)$

Sol
 $x(t) = \cosh \omega_0 t \quad \text{for } t \geq 0$

$$\therefore \cosh \theta = \frac{e^{\theta} + e^{-\theta}}{2}$$

$$L\{x(t)\} = X(s) = \int_{-\infty}^{\infty} x(t) \cdot e^{-st} dt$$

$$= \int_0^{\infty} \left(\frac{e^{\omega_0 t} + e^{-\omega_0 t}}{2} \right) e^{-st} dt$$

$$= \frac{1}{2} \int_0^{\infty} e^{\omega_0 t} \cdot e^{-st} dt + \frac{1}{2} \int_0^{\infty} e^{-\omega_0 t} \cdot e^{-st} dt$$

$$= \frac{1}{2} \left[\int_0^{\infty} e^{-(s-\omega_0)t} dt + \int_0^{\infty} e^{-(s+\omega_0)t} dt \right]$$

$$= \frac{1}{2} \left\{ \left[\frac{e^{-(s-\omega_0)t}}{-(s-\omega_0)} \right]_0^{\infty} + \left[\frac{e^{-(s+\omega_0)t}}{-(s+\omega_0)} \right]_0^{\infty} \right\}$$

$$= \frac{1}{2} \left[\frac{e^{-\infty}}{-(s-\omega_0)} + \frac{1}{s-\omega_0} + \frac{e^{-\infty}}{-(s+\omega_0)} + \frac{1}{s+\omega_0} \right]$$

$$= \frac{1}{2} \left[\frac{1}{s-\omega_0} + \frac{1}{s+\omega_0} \right]$$

$$= \frac{1}{2} \left[\frac{s+\omega_0+s-\omega_0}{s^2-\omega_0^2} \right] = \frac{s}{s^2-\omega_0^2}$$

9) $x(t) = e^{-at} \sin \omega_0 t u(t)$

sol $x(t) = e^{-at} \sin \omega_0 t \text{ for } t \geq 0$

$$\mathcal{L}\{x(t)\} = X(s) = \int_0^{\infty} x(t) \cdot e^{-st} dt = \int_0^{\infty} e^{-at} \sin \omega_0 t e^{-st} dt = \int_0^{\infty} e^{-at} \left(\frac{e^{j\omega_0 t} - e^{-j\omega_0 t}}{2j} \right) e^{-st} dt$$

$$= \frac{1}{2j} \left[\int_0^{\infty} e^{-(s+a-j\omega_0)t} - e^{-(s+a+j\omega_0)t} \right] dt$$

$$= \frac{1}{2j} \left[\left[\frac{e^{-(s+a-j\omega_0)t}}{-(s+a-j\omega_0)} \right]_0^{\infty} - \left[\frac{e^{-(s+a+j\omega_0)t}}{-(s+a+j\omega_0)} \right]_0^{\infty} \right]$$

$$= \frac{1}{2j} \left[\frac{e^{-\infty}}{-(s+a-j\omega_0)} + \frac{e^0}{s+a-j\omega_0} + \frac{e^{-\infty}}{s+a+j\omega_0} - \frac{e^0}{s+a+j\omega_0} \right]$$

$$= \frac{1}{2j} \left[\frac{1}{s+a-j\omega_0} - \frac{1}{s+a+j\omega_0} \right] = \frac{1}{2j} \left[\frac{s+a+j\omega_0 - s-a+j\omega_0}{(s+a)^2 + \omega_0^2} \right]$$

$$= \frac{2j\omega_0}{2j \cdot (s+a)^2 + \omega_0^2}$$

$$= \frac{\omega_0}{(s+a)^2 + \omega_0^2}$$

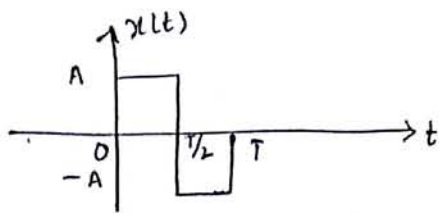
(10) $x(t) = e^{-at} \cos \omega_0 t u(t)$

sol $x(t) = e^{-at} \cos \omega_0 t \text{ for } t \geq 0$

ly $= \frac{s+a}{(s+a)^2 + \omega_0^2}$

(11) Determine the Laplace transform of following signals.

Sol)

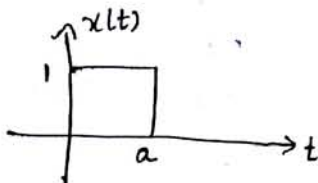


$$x(t) = A \text{ for } 0 < t < T/2$$

$$= -A \text{ for } T/2 < t < T$$

$$\begin{aligned} L\{x(t)\} = X(s) &= \int_0^{T/2} A \cdot e^{-st} dt + \int_{T/2}^T -A \cdot e^{-st} dt \\ &= A \left[\frac{e^{-st}}{-s} \right]_0^{T/2} - A \left[\frac{e^{-st}}{-s} \right]_{T/2}^T \\ &= A \left[\frac{e^{-sT/2}}{-s} + \frac{1}{s} \right] - A \left[\frac{e^{-sT}}{-s} + \frac{e^{-sT/2}}{s} \right] \\ &= -\frac{Ae^{-sT/2}}{s} + \frac{A}{s} + \frac{Ae^{-sT}}{s} - \frac{Ae^{-sT/2}}{s} \\ &= \frac{A}{s} \left[1 + e^{-sT} - 2e^{-sT/2} \right] = \frac{A}{s} \left[1 - e^{-sT/2} \right]^2 \end{aligned}$$

(12)

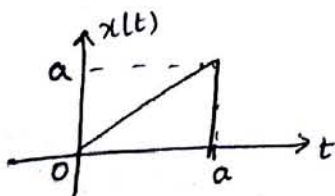


$$x(t) = 1 \text{ for } 0 < t < a$$

$$= 0 \text{ otherwise}$$

$$\begin{aligned} L\{x(t)\} = X(s) &= \int_0^a e^{-st} dt = \left[\frac{e^{-st}}{-s} \right]_0^a \\ &= \frac{e^{-as}}{-s} + \frac{1}{s} \Rightarrow \frac{1}{s} \left[1 - e^{-as} \right] \end{aligned}$$

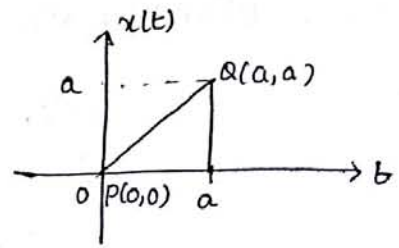
(13)



$$\frac{y-y_1}{y_1-y_2} = \frac{x-x_1}{x_1-x_2}$$

here $(x_1, y_1) = (0, 0)$, $(x_2, y_2) = (a, a)$

$$x = t, y = x(t).$$

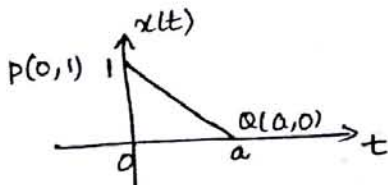


$$\Rightarrow \frac{x(t)-0}{a-0} = \frac{t-0}{0-a} \Rightarrow \frac{x(t)}{-a} = \frac{t}{-a} \Rightarrow x(t) = t \text{ for } 0 \leq t \leq a$$

$$= 0 \text{ otherwise}$$

$$\begin{aligned} \mathcal{L}\{x(t)\} &= X(s) = \int_{-\infty}^{\infty} x(t) \cdot e^{-st} dt \\ &= \int_0^a t e^{-st} dt = \left[t \left[\frac{e^{-st}}{-s} \right]_0^a - \int_0^a \frac{e^{-st}}{-s} dt \right] \\ &= \left[t \cdot \frac{e^{-st}}{-s} \right]_0^a - \left[\frac{e^{-st}}{s^2} \right]_0^a \\ &= a \cdot \frac{e^{-sa}}{-s} - \frac{e^{-as}}{s^2} + \frac{1}{s^2} \\ &= \frac{1}{s^2} \left[1 - e^{-as} - as \cdot e^{-as} \right] \\ &= \frac{1}{s^2} \left[1 - e^{-as} - as \cdot e^{-as} \right] \\ &= \frac{1}{s^2} \left[1 - e^{-as} (1 + as) \right] \end{aligned}$$

114)



$$(x_1, y_1) = (0, 1), (x_2, y_2) = (a, 0), x = t, y = x(t).$$

$$\frac{y-y_1}{y_1-y_2} = \frac{x-x_1}{x_1-x_2} \Rightarrow \frac{x(t)-1}{1-0} = \frac{t-0}{0-a} \Rightarrow x(t)-1 = \frac{-t}{a}$$

$$x(t) = 1 - t/a \text{ for } 0 \leq t \leq a$$

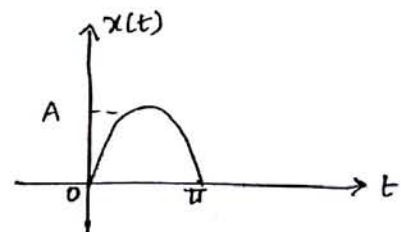
$$= 0 \text{ for } t > a$$

$$\begin{aligned}
L\{x(t)\} &= X(s) = \int_{-\infty}^{\infty} x(t) \cdot e^{-st} dt \\
&= \int_0^a \left(1 - \frac{t}{a}\right) e^{-st} dt = \int_0^a e^{-st} dt - \int_0^a \frac{t}{a} e^{-st} dt \\
&= \left[\frac{e^{-st}}{-s} \right]_0^a - \frac{1}{a} \left[\int_0^a t \cdot e^{-st} dt \right] \\
&= \frac{e^{-as}}{-s} + \frac{1}{s} - \frac{1}{a} \left[t \cdot \frac{e^{-st}}{-s} - \frac{e^{-st}}{s^2} \right]_0^a \\
&= \frac{e^{-as}}{-s} + \frac{1}{s} - \frac{1}{a} \cdot \left[\frac{t \cdot e^{-st}}{-s} - \frac{e^{-st}}{s^2} \right]_0^a \\
&= \frac{e^{-as}}{-s} + \frac{1}{s} - \frac{1}{a} \cdot \left[\frac{a \cdot e^{-as}}{-s} + \frac{1 \cdot e^{-sa}}{as^2} - \frac{1}{as^2} \right] \\
&= \frac{e^{-as}}{-s} + \frac{1}{s} + \frac{e^{-as}}{s} + \frac{e^{-as}}{as^2} - \frac{1}{as^2} \\
&= \frac{1}{s} + \frac{e^{-as}}{as^2} - \frac{1}{as^2} = \frac{1}{as^2} [e^{-as} + as - 1]
\end{aligned}$$

(15) Determine the Laplace transform of sine pulse

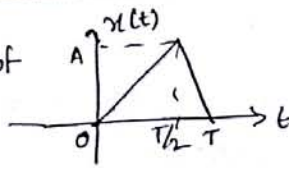
Sol

$$\begin{aligned}
x(t) &= A \sin t \quad \text{for } 0 < t < \pi \\
&= 0 \quad \text{for } t > \pi
\end{aligned}$$



$$\begin{aligned}
L\{x(t)\} &= X(s) = \int_0^{\pi} A \cdot \sin t \cdot e^{-st} dt \\
&= A \left[\frac{e^{jt} - e^{-jt}}{2j} \cdot e^{-st} \right] dt = \frac{A}{2j} \left[\int_0^{\pi} e^{-(s-j)t} dt - \int_0^{\pi} e^{-(s+j)t} dt \right] \\
&= \frac{A}{2j} \left[\frac{e^{-(s-j)t}}{-(s-j)} \right]_0^{\pi} - \frac{A}{2j} \left[\frac{e^{-(s+j)t}}{-(s+j)} \right]_0^{\pi} \\
&= \frac{A}{2j} \left[\frac{e^{-(s+j)t}}{s+j} - \frac{e^{-(s-j)t}}{s-j} \right]_0^{\pi} = \frac{A}{2j} \left[\frac{(s-j)e^{-st}e^{-jt} - (s+j)e^{-st}e^{jt}}{s^2 - j^2} \right]_0^{\pi} \\
&= \frac{A}{2j(s^2 + 1)} \left[(s-j)e^{-st}e^{-jt} - (s+j)e^{-st}e^{jt} \right]_0^{\pi} \\
&= \frac{A}{2j(s^2 + 1)} \left[(s-j)e^{-s\pi}e^{-j\pi} - (s+j)e^{-s\pi}e^{j\pi} - (s-j)e^{-s \cdot 0}e^{-j \cdot 0} + (s+j)e^{-s \cdot 0}e^{j \cdot 0} \right] \\
&= \frac{A}{2j(s^2 + 1)} \left[-(s-j)e^{-s\pi} + (s+j)e^{-s\pi} - (s-j) + (s+j) \right] = \frac{A}{2j(s^2 + 1)} (2je^{j\pi s} + 2j) \\
&\Rightarrow \frac{A}{s^2 + 1} (e^{j\pi s} + 1)
\end{aligned}$$

(16) Determine Laplace transform of



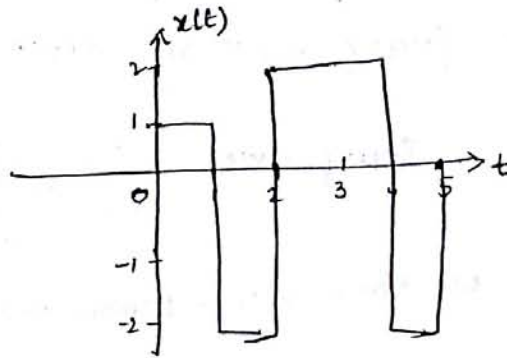
Sol

$$x(t) = \frac{2At}{T} ; 0 < t < T/2$$

$$= 2A - \frac{2At}{T} \quad T/2 < t < T$$

$$L\{x(t)\} = x(s) = \frac{2A}{Ts} \left(1 - e^{-sT/2}\right)$$

(17) Determine Laplace transform of



Sol

$$x(t) = \begin{cases} 1 & \text{for } 0 < t < 1 \\ -2 & \text{for } 1 < t < 2 \\ 2 & \text{for } 2 < t < 4 \\ -2 & \text{for } 4 < t < 5 \\ 0 & \text{for } t > 5 \end{cases}$$

$$\begin{aligned} L\{x(t)\} = x(s) &= \int_0^1 e^{-st} dt + \int_1^2 -2e^{-st} dt + \int_2^4 2e^{-st} dt + \int_4^5 -2e^{-st} dt \\ &= \left[\frac{e^{-st}}{-s} \right]_0^1 - 2 \left[\frac{e^{-st}}{-s} \right]_1^2 + 2 \left[\frac{e^{-st}}{-s} \right]_2^4 - 2 \left[\frac{e^{-st}}{-s} \right]_4^5 \\ &= \frac{e^{-s}}{-s} + \frac{1}{s} + \frac{2e^{-2s}}{s} - \frac{e^{-s}}{s} - \frac{2e^{-4s}}{s} + \frac{2e^{-2s}}{s} + \frac{2e^{-5s}}{s} - \frac{2e^{-4s}}{s} \\ &= \frac{1}{s} \left[1 - 2e^{-s} + 4e^{-2s} - 4e^{-4s} + 2e^{-5s} \right] \end{aligned}$$

(18) Determine the Laplace transform of $\delta(t)$.

Sol

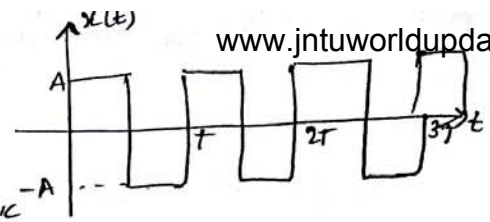
$$\delta(t) = 1 \text{ for } t=0 \\ = 0 \text{ otherwise.}$$

$$L\{x(t)\} = x(s) = \left. \frac{e^{-st}}{-s} \right|_{t=0} =$$

Determine the Laplace transform of periodic square wave

The given waveform satisfy the condition

$x(t+nT) = x(t)$ and so it is periodic



$$x_1(t) = A \text{ for } t = 0 \text{ to } T/2$$

$$= -A \text{ for } t = T/2 \text{ to } T$$

From periodicity property of Laplace transform

$$\text{If } X(s) = \mathcal{L}\{x(t)\} \text{ and if } x(t) = x(t+nT) \text{ then } X(s) = \frac{1}{1-e^{-sT}} \int_0^T x_1(t) e^{-st} dt$$

$$\therefore \mathcal{L}\{x(t)\} = X(s) = \frac{1}{1-e^{-sT}} \int_0^T x_1(t) e^{-st} dt$$

$$\text{we know } x_1(t) = \text{Laplace transform} = \frac{A}{s} \left[1 - e^{-sT/2} \right]^r$$

$$X(s) = \frac{1}{1-e^{-sT}} \left[\frac{A}{s} \left(1 - e^{-sT/2} \right)^r \right]^\infty$$

$$= \frac{1}{(1-e^{-sT/2})(1+e^{-sT/2})} \left[\frac{A}{s} \left(1 - e^{-sT/2} \right)^r \right]$$

$$= \frac{A}{s} \left[\frac{1 - e^{-sT/2}}{1 + e^{-sT/2}} \right]$$

(7)

Initial Value Theorem:

The initial value theorem states that, if $x(t)$ and its derivative are Laplace transformable then $\lim_{t \rightarrow 0} x(t) = \lim_{s \rightarrow \infty} sX(s)$.

$$\text{i.e. } x(0) = \lim_{t \rightarrow 0} x(t) = \lim_{s \rightarrow \infty} sX(s).$$

Proof

We know that

$$L\left\{\frac{dx(t)}{dt}\right\} = sX(s) - x(0)$$

On taking limits $s \rightarrow \infty$ on both sides of equation.

$$\lim_{s \rightarrow \infty} L\left\{\frac{dx(t)}{dt}\right\} = \lim_{s \rightarrow \infty} [sX(s) - x(0)]$$

$$\Rightarrow \lim_{s \rightarrow \infty} \int_0^{\infty} \frac{dx(t)}{dt} e^{-st} dt = \lim_{s \rightarrow \infty} [sX(s) - x(0)]$$

$$\Rightarrow \int_0^{\infty} \frac{dx(t)}{dt} \left(\lim_{s \rightarrow \infty} e^{-st} \right) dt = \lim_{s \rightarrow \infty} sX(s) - x(0)$$

$$\Rightarrow 0 = \lim_{s \rightarrow \infty} sX(s) - x(0)$$

$$\therefore x(0) = \lim_{s \rightarrow \infty} sX(s).$$

$$\boxed{\therefore \lim_{t \rightarrow 0} x(t) = \lim_{s \rightarrow \infty} sX(s)}$$

Final value theorem:

The final value theorem states that if $x(t)$ and its derivative are Laplace transformable then $\lim_{t \rightarrow \infty} x(t) = \lim_{s \rightarrow 0} sX(s)$.

$$\text{i.e. Final value of signal } x(\infty) = \lim_{t \rightarrow \infty} x(t) = \lim_{s \rightarrow 0} sX(s).$$

Proof

$$L\left\{\frac{dx(t)}{dt}\right\} = sX(s) - x(0)$$

By taking limits $s \rightarrow 0$ on both sides of above eqn we get

$$\lim_{s \rightarrow 0} L\left\{\frac{dx(t)}{dt}\right\} = \lim_{s \rightarrow 0} [sX(s) - x(0)]$$

$$\lim_{s \rightarrow 0} \int_0^{\infty} \frac{dx(t)}{dt} e^{-st} dt = \lim_{s \rightarrow 0} [sx(s) - x(0)]$$

$$\int_0^{\infty} \frac{dx(t)}{dt} \left(\lim_{s \rightarrow 0} e^{-st} \right) dt = \lim_{s \rightarrow 0} [sx(s) - x(0)]$$

↙
not fn of 's'

Z - TRANSFORMS :

FUNDAMENTAL DIFFERENCES BETWEEN CONTINUOUS & DISCRETE TIME SIGNAL
(Ref Unit - I page No: 9)

→ DISCRETE TIME SIGNAL REPRESENTATION USING COMPLEX EXPONENTIAL AND SINUSOIDAL COMPONENTS.
(Ref Unit - I - page No: 10, 11, 12)

→ PERIODICITY PROPERTIES OF DT COMPLEX FUNCTIONS:

→ A DT complex exponential is periodic if it repeats after certain 'N' number of samples.

consider $x(n) = e^{j\omega_0 n}$

$$\therefore x(n+N) = e^{j\omega_0(n+N)} \\ = e^{j\omega_0 n} \cdot e^{j\omega_0 N}$$

For periodicity $x(n) = x(n+N)$

$$\text{i.e. } e^{j\omega_0 n} = e^{j\omega_0 n} \cdot e^{j\omega_0 N} \Rightarrow e^{j\omega_0 N} = 1$$

Expressing $e^{j\omega_0 N}$ in terms of sinusoidal functions

$$e^{j\omega_0 N} = \cos \omega_0 N + j \sin \omega_0 N \text{ by Euler's identity}$$

$$e^{j0} = \cos 0 + j \sin 0$$

→ For periodicity $e^{j\omega_0 N} = 1$ gives $\cos \omega_0 N + j \sin \omega_0 N = 1$. This eqn is satisfied for

$$\omega_0 N = 2\pi, 4\pi, 6\pi, 8\pi \dots$$

$$= 2\pi K \text{ where } K = \text{integer}$$

$$\text{(OR)} \quad \frac{\omega_0}{2\pi} = \frac{K}{N} \rightarrow \textcircled{1}$$

$$\text{but } \omega_0 = 2\pi f \Rightarrow \frac{\omega_0}{2\pi} = f \rightarrow \textcircled{2}$$

Substitute (2) in (1)

$$f = \frac{K}{N}$$

∴ For complex exponential to be periodic, $\frac{\omega_0}{2\pi} = \frac{K}{N}$ (i.e. rational)

Z-TRANSFORM (CONCEPT):

The z-transform of $x(n)$ is denoted by $X(z)$ and defined as

$$X(z) = \sum_{n=-\infty}^{\infty} x(n) z^{-n} \rightarrow \text{where } z \text{ is complex variable.}$$

→ $x(n)$ & $X(z)$ is called z-transform pair represented as

$$x(n) \xleftrightarrow{z} X(z).$$

→ Purpose of learning z-transform is to analyse the DT signals and systems, digital filter design and for synthesis of digital filter / systems.

→ For any input sequence, the z-transform is complex. It has real & imaginary parts.

DISTINCTION BETWEEN LAPLACE, FOURIER AND Z TRANSFORM:

z-transform given as

$$X(z) = \sum_{n=-\infty}^{\infty} x(n) z^{-n} \quad \text{ROC: } r_2 < |z| < r_1$$

where 'z' is defined as $z = r e^{j\omega}$ in which 'r' is magnitude of z i.e. $|z|$ and ω = angle of z i.e. $\angle z$

→ putting for $z = r e^{j\omega}$ in $X(z)$ we get

$$\begin{aligned} X(z) &= \sum_{n=-\infty}^{\infty} x(n) (r e^{j\omega})^{-n} \\ &= \sum_{n=-\infty}^{\infty} [x(n) r^{-n}] e^{-j\omega n} \rightarrow \textcircled{1} \end{aligned}$$

→ Fourier transform is given by $X(\omega) = \sum_{n=-\infty}^{\infty} x(n) e^{-j\omega n} \rightarrow \textcircled{2}$ comparing $X(\omega)$ with $X(z)$ we find that $X(z)$ indicates Fourier transform of $x(n) r^{-n}$.

→ Let $x(z)$ of eq ① is evaluated on unit circle. Then $|z| = r = 1$ i.e. $r^{-n} = 1$

$$\therefore x(z) \big|_{z=e^{j\Omega}} = \sum_{n=-\infty}^{\infty} x(n) e^{-j\Omega n} \rightarrow \text{Fourier transform by definition}$$

$$\boxed{x(z) \big|_{z=e^{j\Omega}} = x(j\Omega)} \rightarrow \text{R/Bct/n FT \(\nleftrightarrow\) Z-T}$$

→ Laplace Transform of i/p sgl $x(t)$ defined as

$$\mathcal{L}\{x(t)\} = X(s) = \int_0^{\infty} x(t) e^{-st} dt \rightarrow \text{①}$$

On substituting $s = \sigma + j\Omega$ in above eqn ①

$$\mathcal{L}\{x(t)\} = X(s) = \int_{-\infty}^{\infty} x(t) e^{-(\sigma + j\Omega)t} dt \rightarrow \text{②}$$

but definition of fourier transform of $x(t)$ is

$$F\{x(t)\} = X(j\Omega) = \int_{-\infty}^{\infty} x(t) \cdot e^{-j\Omega t} dt \rightarrow \text{③}$$

By comparing equations ② & ③, we can say that

By putting $\sigma = 0$ in laplace transform we get fourier transform of continuous time signal.

$$\therefore X(j\Omega) = X(s) \big|_{s=j\Omega}$$

REGION OF CONVERGENCE IN Z-TRANSFORM:

→ Since z-transform is an infinite power series, it exists only for those values of z for which the series converges.

→ The ROC of $x(z)$ is the set of all values of z , for which $x(z)$ attains a finite value.

CONSTRAINTS ON ROC FOR VARIOUS CLASSES OF SIGNALS: (OR)

PROPERTIES OF ROC with proofs:

- (1) The ROC is a ring or disk in the z -plane centered at the origin.
- (2) The ROC cannot contain any poles.
- (3) If $x(n)$ is a finite duration, causal sequence then the ROC is the entire z -plane except at $z=0$.
- (4) If $x(n)$ is a finite duration, anti-causal sequence then the ROC is the entire z -plane except at $z=\infty$.
- (5) If $x(n)$ is a finite duration, two sided sequence then the ROC is entire z -plane except at $z=0$ & $z=\infty$.
- (6) If $x(n)$ is an infinite duration, two sided sequence the ROC will consist of a ring in z -plane, bounded on interior and exterior by a pole not containing any poles.
- (7) The ROC of an LTI stable system contains unit circle.
- (8) The ROC must be connected region.

Case i) Finite duration, right sided (causal) signal:

Let $x(n)$ be finite duration signal with N -samples, defined in range $0 \leq n \leq (N-1)$

$$\therefore x(n) = \{x(0), x(1), x(2), \dots, x(N-1)\}$$

$$\begin{aligned} X(z) &= \sum_{n=0}^{N-1} x(n) z^{-n} \\ &= x(0) + x(1)z^{-1} + \dots + x(N-1)z^{-(N-1)} \\ &= x(0) + \frac{x(1)}{z} + \frac{x(2)}{z^2} + \dots + \frac{x(N-1)}{z^{N-1}} \end{aligned}$$

When $z=0$, all the terms except the first term become infinite.

Hence the $X(z)$ exists for all values of z except $z=0$.

$\therefore$ ROC for finite duration right sided is entire z -plane except $z=0$

Case ii) Finite duration, left sided (anticausal) signal:

Let $x(n)$ be finite duration signal with N -samples, defined in the range $-(N-1) \leq n < 0$

$$\therefore x(n) = \{x(-(N-1)), \dots, x(-2), x(-1), x(0)\}$$

z -transform of $x(n)$ is

$$X(z) = \sum_{n=-(N-1)}^0 x(n) z^{-n}$$

$$X(z) = x(-(N-1)) z^{(N-1)} + \dots + x(-2) z^2 + x(-1) z + x(0)$$

when $z = \infty$, all terms except the last term become infinite. Hence the $X(z)$ exists for all values of z , except $z = \infty$.

$\therefore$ ROC of $X(z)$ is entire z -plane except $z = \infty$.

Case iii) Finite duration, two sided (non-causal) signal:

Let $x(n)$ be a finite duration signal with N -samples, defined in the range $-M \leq n \leq M$ where $M = \frac{N-1}{2}$.

$$\therefore x(n) = \{x(-M), \dots, x(-2), x(-1), x(0), x(1), x(2), \dots, x(M)\}$$

z -transform of $x(n)$ is

$$X(z) = \sum_{n=-M}^M x(n) z^{-n}$$

$$= x(-M) z^M + \dots + x(-2) z^2 + x(-1) z + x(0) + x(1) z^{-1} +$$

$$x(2) z^{-2} + \dots + x(M) z^{-M}$$

$$= x(-M) z^M + \dots + x(-2) z^2 + x(-1) z + x(0) + \frac{x(1)}{z} + \frac{x(2)}{z^2} + \dots + \frac{x(M)}{z^M}$$

when $z = 0$, the terms with negative power of z attain infinity and when $z = \infty$, the terms with positive power of z attain infinity. Hence $X(z)$ converges for all values of z , except at $z = 0$ & $z = \infty$.

ROC is entire z -plane except $z = 0$ & $z = \infty$.

Case iv) Infinite duration, right sided (causal) signal:

$$\text{Let } x(n) = r_1^n ; n \geq 0$$

$$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n} = \sum_{n=0}^{\infty} r_1^n z^{-n} = \sum_{n=0}^{\infty} (r_1 z^{-1})^n$$

$$\text{If } 0 < |r_1 z^{-1}| < 1, \text{ then } \sum_{n=0}^{\infty} (r_1 z^{-1})^n = \frac{1}{1 - r_1 z^{-1}}$$

$$\therefore X(z) = \frac{1}{1 - \frac{r_1}{z}} = \frac{z}{z - r_1}$$

Using infinite geometric series sum formula

$$\sum_{n=0}^{\infty} c_n = \frac{1}{1 - c}$$

$$\text{if } 0 < |c| < 1$$

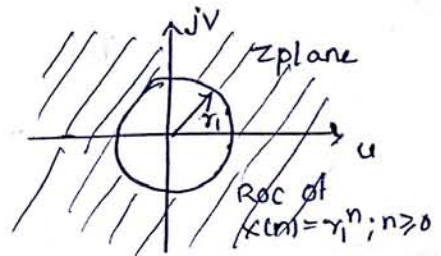
Condition to be satisfied for convergence of $X(z)$ is

$$0 < |r_1 z^{-1}| < 1$$

$$\therefore |r_1 z^{-1}| < 1$$

$$\frac{|r_1|}{|z|} < 1 \Rightarrow |z| > |r_1|$$

represent a circle of radius r_1 in z -plane.



$\rightarrow X(z)$ converges for all points external to the circle of radius r_1 in z -plane.

$\therefore$ ROC of $X(z)$ is exterior of the circle of radius r_1 in z -plane.

Case v) : Infinite duration, left sided (anticausal) signal:

$$\text{Let } x(n) = r_2^n ; n \leq 0$$

$$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n} = \sum_{n=0}^{\infty} r_2^n z^{-n} = \sum_{n=0}^{\infty} (r_2^{-1} z)^n$$

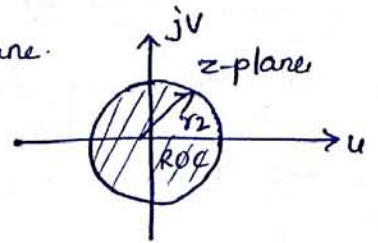
$$\text{If } 0 < |r_2^{-1} z| < 1 \text{ then } \sum_{n=0}^{\infty} (r_2^{-1} z)^n = \frac{1}{1 - r_2^{-1} z}$$

$$\begin{aligned} \therefore X(z) &= \frac{1}{1 - r_2^{-1} z} = \frac{1}{1 - \frac{z}{r_2}} = \frac{r_2}{r_2 - z} \\ &= \frac{-r_2}{z - r_2} \end{aligned}$$

Condition to be satisfied for convergence of $X(z)$ is

$$0 < |r_2^{-1} z| < 1 \Rightarrow |r_2^{-1} z| < 1 \Rightarrow \frac{|z|}{|r_2|} < 1 \Rightarrow |z| < |r_2|$$

The term $|r_2|$ represent a circle of radius of r_2 in z -plane.
 $x(z)$ converges for all pts internal to the circle of radius r_2 in z -plane. $\therefore$ ROC of $x(z)$ is interior of the circle of radius r_2 .



Case vi) Infinite duration, two sided (anticausal) signal:

$$\text{Let } x(n) = r_1^n u(n) + r_2^n u(-n)$$

$$X(z) = \sum_{n=-\infty}^{\infty} x(n) z^{-n} = \sum_{n=-\infty}^{\infty} r_2^n z^{-n} + \sum_{n=0}^{\infty} r_1^n z^{-n}$$

$$= \sum_{n=0}^{\infty} r_2^{-n} z^n + \sum_{n=0}^{\infty} r_1^n z^{-n}$$

$$= \sum_{n=0}^{\infty} (r_2^{-1} z)^n + \sum_{n=0}^{\infty} (r_1 z^{-1})^n$$

$$= \frac{1}{1 - r_2^{-1} z} + \frac{1}{1 - r_1 z^{-1}}$$

Using infinite geometric series sum formula
 if $0 < |r_2^{-1} z| < 1$ & $0 < |r_1 z^{-1}| < 1$

The term $\sum_{n=0}^{\infty} (r_2^{-1} z)^n$ converges if

$$0 < |r_2^{-1} z| < 1$$

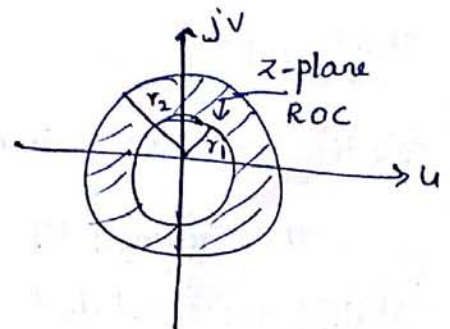
$$\therefore |r_2^{-1} z| < 1 \Rightarrow \frac{|z|}{|r_2|} < 1 \Rightarrow |z| < |r_2|.$$

The term $\sum_{n=0}^{\infty} (r_1 z^{-1})^n$ converges if

$$0 < |r_1 z^{-1}| < 1$$

$$\therefore |r_1 z^{-1}| < 1$$

$$\frac{|r_1|}{|z|} < 1 \Rightarrow |z| > |r_1|.$$



$\therefore$ ROC is the region between two circles of radius r_1 & r_2 .

PROPERTIES OF Z-TRANSFORM:

Linearity Property:

→ States that z-transform of linear weighted combination of discrete time signals is equal to similar linear weighted combination of z transform of individual discrete time signals.

Let $Z\{x_1(n)\} = x_1(z)$ and $Z\{x_2(n)\} = x_2(z)$ then by linearity property

$$Z\{a_1 x_1(n) + a_2 x_2(n)\} = a_1 x_1(z) + a_2 x_2(z) \quad (a_1, a_2 \text{ are constants}).$$

proof:

z-transform definition

$$x_1(z) = Z\{x_1(n)\} = \sum_{n=-\infty}^{\infty} x_1(n) z^{-n}$$

$$x_2(z) = Z\{x_2(n)\} = \sum_{n=-\infty}^{\infty} x_2(n) z^{-n}$$

$$\begin{aligned} Z\{a_1 x_1(n) + a_2 x_2(n)\} &= \sum_{n=-\infty}^{\infty} [a_1 x_1(n) + a_2 x_2(n)] z^{-n} \\ &= \sum_{n=-\infty}^{\infty} [a_1 x_1(n) z^{-n} + a_2 x_2(n) z^{-n}] \\ &= \sum_{n=-\infty}^{\infty} a_1 x_1(n) z^{-n} + \sum_{n=-\infty}^{\infty} a_2 x_2(n) z^{-n} \\ &= a_1 \sum_{n=-\infty}^{\infty} x_1(n) z^{-n} + a_2 \sum_{n=-\infty}^{\infty} x_2(n) z^{-n} \\ &= a_1 x_1(z) + a_2 x_2(z). \end{aligned}$$

Shifting property:

Case i) Two sided z-transform

The shifting property of z-transform states that z-transform of a shifted signal shifted by 'm' units of time is obtained by multiplying z^m to z-transform of unshifted signal.

$$\text{Let } Z\{x(n)\} = X(z) \text{ then } Z\{x(n-m)\} = z^{-m} X(z) \quad \& \quad Z\{x(n+m)\} = z^m X(z)$$

Proof:

$$x(z) = \mathcal{Z}\{x(n)\} = \sum_{n=-\infty}^{\infty} x(n) z^{-n}$$

$$\mathcal{Z}\{x(n-m)\} = \sum_{n=-\infty}^{\infty} x(n-m) z^{-n}$$

$$= \sum_{p=-\infty}^{\infty} x(p) z^{-(m+p)}$$

$$= \sum_{p=-\infty}^{\infty} x(p) z^{-p} \cdot z^{-m}$$

$$= z^{-m} \sum_{p=-\infty}^{\infty} x(p) z^{-p} = z^{-m} x(z)$$

$$\left\{ \begin{array}{l} \text{Let } n-m=p \therefore n=p+m \\ \text{when } n \rightarrow -\infty, p \rightarrow -\infty \\ n \rightarrow \infty, p \rightarrow \infty \end{array} \right.$$

$$\mathcal{Z}\{x(n+m)\} = \sum_{n=-\infty}^{\infty} x(n+m) z^{-n}$$

$$= \sum_{p=-\infty}^{\infty} x(p) z^{-(p-m)}$$

$$= \sum_{p=-\infty}^{\infty} x(p) z^{-p} \cdot z^m$$

$$= z^m \sum_{p=-\infty}^{\infty} x(p) z^{-p} \quad (\because \text{if } p \rightarrow n)$$

$$= z^m \cdot x(z)$$

Case ii) One sided Z-transform:Let $x(n)$ be discrete time signal defined in range $0 < n < \infty$

$$\mathcal{Z}\{x(n)\} = x(z)$$

By shifting property

$$\mathcal{Z}\{x(n-m)\} = z^{-m} x(z) + \sum_{i=1}^m x(-i) z^{-(m-i)}$$

$$\mathcal{Z}\{x(n+m)\} = z^m x(z) - \sum_{i=0}^{m-1} x(i) z^{(m-i)}$$

Proof

$$x(z) = z\{x(n)\} = \sum_{n=0}^{\infty} x(n)z^{-n}$$

$$z\{x(n-m)\} = \sum_{n=0}^{\infty} x(n-m)z^{-n}$$

multiply by z^m & z^{-m}

$$= \sum_{n=0}^{\infty} x(n-m)z^{-n}z^m z^{-m}$$

$$= z^{-m} \sum_{n=0}^{\infty} x(n-m)z^{-(n-m)}$$

$$= z^{-m} \sum_{p=-m}^{\infty} x(p)z^{-p} \quad \left\{ \begin{array}{l} \text{Let } n-m=p \end{array} \right.$$

$$= z^{-m} \sum_{p=0}^{\infty} x(p)z^{-p} + \sum_{p=-m}^{-1} x(p)z^{-p} \cdot z^{-m}$$

$$= z^{-m} \sum_{p=0}^{\infty} x(p)z^{-p} + z^{-m} \sum_{p=1}^m x(-p)z^p$$

$$= z^{-m} \sum_{n=0}^{\infty} x(n)z^{-n} + z^{-m} \sum_{i=1}^m x(-i)z^i$$

Let $p=n$, in 1st summation
 $p=i$ in 2nd "

$$= z^m x(z) + \sum_{i=1}^m x(-i)z^{-(m-i)}$$

$$z\{x(n+m)\} = \sum_{n=0}^{\infty} x(n+m)z^{-n} = \sum_{n=0}^{\infty} x(n+m)z^{-n}z^m z^{-m} \quad (\text{multiply by } z^m \& z^{-m})$$

$$= z^m \sum_{n=0}^{\infty} x(n+m)z^{-(n+m)}$$

$$= z^m \sum_{p=m}^{\infty} x(p)z^{-p}$$

Let $n+m=p$
when $n \rightarrow 0$, $p \rightarrow m$
 $n \rightarrow \infty$, $p \rightarrow \infty$

$$= z^m \sum_{p=0}^{\infty} x(p)z^{-p} - z^m \sum_{p=0}^{m-1} x(p)z^{-p}$$

$$= z^m \sum_{n=0}^{\infty} x(n)z^{-n} - z^m \sum_{i=0}^{m-1} x(i)z^{-i}$$

$$= z^m x(z) - \sum_{i=0}^{m-1} x(i)z^{m-i} \quad \left\{ \begin{array}{l} \text{Let } p=n \text{ in 1st} \\ p=i \text{ in 2nd.} \end{array} \right.$$

(3) Multiplication by n (or Differentiation in z-domain)

proof If $z\{x(n)\} = X(z)$ then $z\{nx(n)\} = -z \frac{d}{dz} X(z)$

In general $z\{n^m x(n)\} = \left(-z \frac{d}{dz}\right)^m X(z)$

$$X(z) = z\{x(n)\} = \sum_{n=-\infty}^{\infty} x(n) z^{-n}$$

$$z\{nx(n)\} = \sum_{n=-\infty}^{\infty} nx(n) z^{-n} = \sum_{n=-\infty}^{\infty} nx(n) z^{-n} z z^{-1}$$

$$= -z \sum_{n=-\infty}^{\infty} x(n) [-nz^{-n-1}]$$

$$= -z \sum_{n=-\infty}^{\infty} x(n) \left[\frac{d}{dz} z^{-n} \right]$$

$$\left\{ \because \frac{d}{dz} z^{-n} = -nz^{-n-1} \right.$$

$$= -z \frac{d}{dz} \sum_{n=-\infty}^{\infty} x(n) z^{-n}$$

$$z\{nx(n)\} = -z \frac{d}{dz} X(z)$$

$\left\{ \begin{array}{l} \text{Interchanging} \\ \text{summation \& differentiation} \end{array} \right.$

(4) Multiplication by an exponential sequence, a^n (scaling in z-domain)

If $z\{x(n)\} = X(z)$ then $z\{a^n x(n)\} = X(a^{-1}z)$

proof

$$z\{x(n)\} = \sum_{n=-\infty}^{\infty} x(n) z^{-n}$$

$$z\{a^n x(n)\} = \sum_{n=-\infty}^{\infty} a^n x(n) z^{-n}$$

$$= \sum_{n=-\infty}^{\infty} x(n) (a^{-1}z)^{-n}$$

$$= \sum_{n=-\infty}^{\infty} x(n) (a^{-1}z)^{-n}$$

$$= X(a^{-1}z)$$

(5) Time Reversal :

If $z\{x(n)\} = x(z)$ then $z\{x(-n)\} = x(z^{-1})$

proof

$$z\{x(n)\} = \sum_{n=-\infty}^{\infty} x(n) z^{-n}$$

$$z\{x(-n)\} = \sum_{n=-\infty}^{\infty} x(-n) z^{-n}$$

$$= \sum_{p=-\infty}^{\infty} x(p) z^p$$

$$= \sum_{p=-\infty}^{\infty} x(p) (z^{-1})^{-p}$$

$$= x(z^{-1})$$

$$\left\{ \begin{array}{l} \text{Let } p = -n \\ \text{when } n \rightarrow -\infty, p \rightarrow \infty \\ \quad \quad \quad n \rightarrow \infty, p \rightarrow -\infty \end{array} \right.$$

(6) Conjugation :

If $z\{x(n)\} = x(z)$ then $z\{x^*(n)\} = x^*(z^*)$

proof

$$x(z) = z\{x(n)\} = \sum_{n=-\infty}^{\infty} x(n) z^{-n}$$

$$z\{x^*(n)\} = \sum_{n=-\infty}^{\infty} x^*(n) z^{-n}$$

$$= \left[\sum_{n=-\infty}^{\infty} x(n) (z^*)^{-n} \right]^*$$

$$= [x(z^*)]^*$$

$$= x^*(z^*)$$

INVERSE Z-TRANSFORM:

Let $x(z)$ be z-transform of discrete time signal $x(n)$. The inverse z-transform is the process of recovering the discrete time sigl $x(n)$ from its z-transform $x(z)$.

→ The signal $x(n)$ can be uniquely determined from $x(z)$ & its ROC.

It can be determined by three methods

- (i) Direct evaluation by contour integration (or residue method)
- (ii) partial fraction expansion method
- (iii) power series expansion method.

① Determine the inverse z-transform of fn $x(z) = \frac{3+2z^{-1}+z^{-2}}{1-3z^{-1}+2z^{-2}}$ by following three methods and prove that it is unique.

Sol (i) Residue Method:

$$x(z) = \frac{3+2z^{-1}+z^{-2}}{1-3z^{-1}+2z^{-2}} = \frac{z^2(3z^2+2z+1)}{z^2(z^2-3z+2)}$$

$$\therefore x(z) = \frac{3z^2+2z+1}{z^2-3z+2}$$

$$= 3 + \frac{11z-5}{z^2-3z+2}$$

$$= 3 + \frac{11z-5}{(z-1)(z-2)}$$

$$\begin{array}{r} 3 \\ z^2-3z+2 \overline{) 3z^2+2z+1} \\ \underline{+3z^2-9z+6} \\ 11z-5 \end{array}$$

$$\text{Let } x_1(z) = 3, \quad x_2(z) = \frac{11z-5}{(z-1)(z-2)}; \quad \text{i.e. } x(z) = x_1(z) + x_2(z)$$

$$x(n) = z^{-1}\{x(z)\} = z^{-1}\{x_1(z)\} + z^{-1}\{x_2(z)\}$$

$$= z^{-1}\{3\} + z^{-1}\left\{\frac{11z-5}{(z-1)(z-2)}\right\}$$

$$= 3\delta(n) + \sum_{i=1}^N \left[(z-p_i) x_2(z) z^{n-1} \right]_{z=p_i} \quad \text{Using residue theorem.}$$

$$= 3\delta(n) + (z-1) \left. \frac{11z-5 \cdot z^{n-1}}{(z-1)(z-2)} \right|_{z=1} + (z-2) \cdot \left. \frac{11z-5}{(z-1)(z-2)} \cdot z^{n-1} \right|_{z=2}$$

$$= 3\delta(n) + \frac{11-5}{1-2} (1)^{n-1} + \frac{11 \times 2 - 5}{2-1} 2^{n-1}$$

$$\therefore x(n) = 3\delta(n) - 6u(n-1) + 17(2)^{n-1}u(n-1)$$

$$= 3\delta(n) + [-6 + 17(2)^{n-1}] u(n-1).$$

$$\text{when } n=0, x(0) = 3 - 0 + 0 = 3$$

$$\text{when } n=2, x(2) = 0 - 6 + 17 \times 2^1 = 28$$

$$\text{when } n=1, x(1) = 0 - 6 + 17 \times 2^0 = 11$$

$$\text{when } n=3, x(3) = 0 - 6 + 17 \times 2^2 = 62$$

$$\therefore x(n) = \{3, 11, 28, 62, 130, \dots\}$$

Method 2:

$$x(z) = \frac{3 + 2z^{-1} + z^{-2}}{1 - 3z^{-1} + 2z^{-2}} = \frac{3z^2 + 2z + 1}{z^2 - 3z + 2}$$

$$\therefore \frac{x(z)}{z} = \frac{3z^2 + 2z + 1}{z(z-1)(z-2)}$$

$$\text{Let } \frac{x(z)}{z} = \frac{3z^2 + 2z + 1}{z(z-1)(z-2)} = \frac{A_1}{z} + \frac{A_2}{z-1} + \frac{A_3}{z-2}$$

$$A_1 = z \cdot \left. \frac{x(z)}{z} \right|_{z=0} = z \cdot \left. \frac{3z^2 + 2z + 1}{z(z-1)(z-2)} \right|_{z=0} = 0.5$$

$$A_2 = (z-1) \left. \frac{x(z)}{z} \right|_{z=1} = (z-1) \left. \frac{3z^2 + 2z + 1}{z(z-1)(z-2)} \right|_{z=1} = -6$$

$$A_3 = (z-2) \left. \frac{x(z)}{z} \right|_{z=2} = (z-2) \left. \frac{3z^2 + 2z + 1}{z(z-1)(z-2)} \right|_{z=2} = 8.5$$

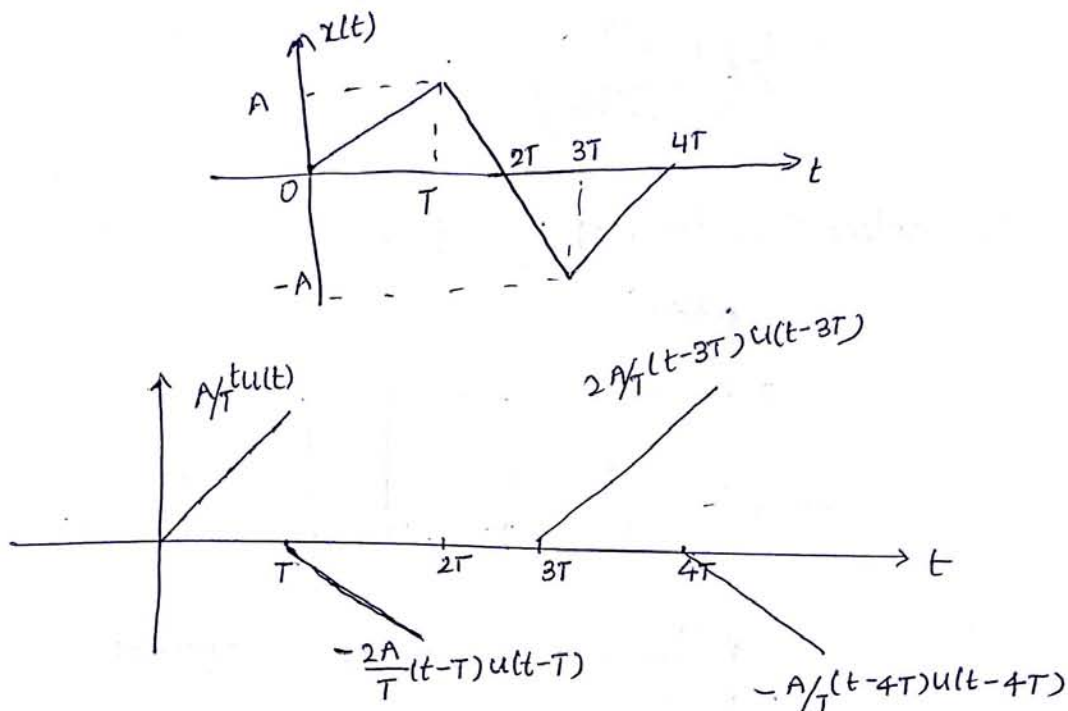
$$\frac{x(z)}{z} = \frac{0.5}{z} - \frac{6}{z-1} + \frac{8.5}{z-2}$$

$$\therefore x(n) = \{3, 11, 28, 62, \dots\}$$

Wave synthesis Using Laplace transform:

To express the function into singular functions and express it in synthesis

① Find the Laplace transform of the waveform.

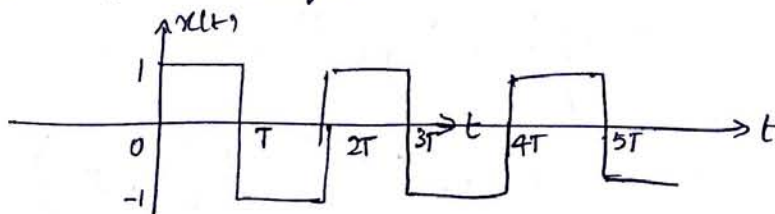


$$x(t) = \frac{A}{T}t u(t) - \frac{2A}{T}(t-T)u(t-T) + \frac{2A}{T}(t-3T)u(t-3T) - \frac{A}{T}(t-4T)u(t-4T)$$

Taking Laplace transform on both sides

$$\begin{aligned} X(s) &= \frac{A}{T} \frac{1}{s^2} - \frac{2A}{T} \frac{e^{-Ts}}{s^2} + \frac{2A}{T} \frac{e^{-3Ts}}{s^2} - \frac{A}{T} \frac{e^{-4Ts}}{s^2} \\ &= \frac{A}{Ts^2} \left[1 - 2e^{-Ts} + 2e^{-3Ts} - e^{-4Ts} \right] \end{aligned}$$

② Find the Laplace transform

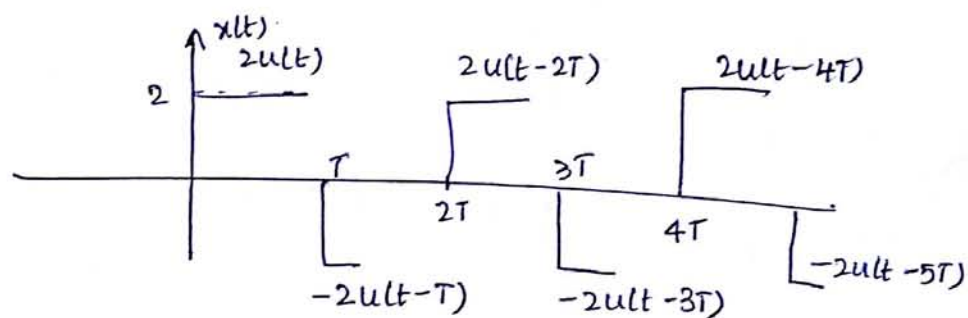
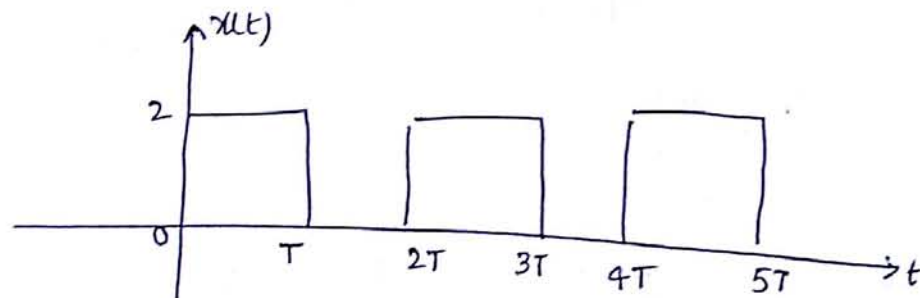


$$x(t) = u(t) - 2u(t-T) + 2u(t-2T) - 2u(t-3T) + 2u(t-4T) - 2u(t-5T) + \dots$$

$$X(s) = \frac{1}{s} - 2 \frac{e^{-Ts}}{s} + \frac{2e^{-2Ts}}{s} - \frac{2e^{-3Ts}}{s} + \frac{2e^{-4Ts}}{s} - \frac{2e^{-5Ts}}{s} + \dots$$

$$\begin{aligned}
 &= \frac{1}{s} \left[1 - 2e^{-Ts} (1 - e^{-Ts} + e^{-2Ts} - e^{-3Ts} + e^{-4Ts} - \dots) \right] \\
 &= \frac{1}{s} \left[1 - 2e^{-Ts} (1 + e^{-Ts})^{-1} \right] = \frac{1}{s} \left(1 - \frac{2e^{-Ts}}{1 + e^{-Ts}} \right) = \frac{1}{s} \left(\frac{1 + e^{-Ts} - 2e^{-Ts}}{1 + e^{-Ts}} \right) \\
 &= \frac{1}{s} \left(\frac{1 - e^{-Ts}}{1 + e^{-Ts}} \right)
 \end{aligned}$$

③ Find the Laplace transform of waveform



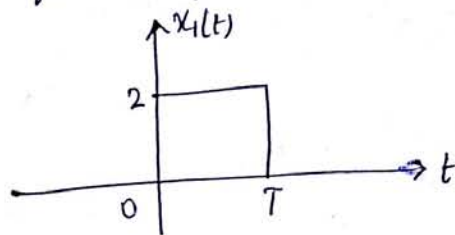
$$x(t) = 2u(t) - 2u(t-T) + 2u(t-2T) - 2u(t-3T) + 2u(t-4T) - 2u(t-5T) + \dots$$

Taking Laplace transform

$$\begin{aligned}
 X(s) &= \frac{2}{s} - \frac{2e^{-Ts}}{s} + \frac{2e^{-2Ts}}{s} - \frac{2e^{-3Ts}}{s} + \frac{2e^{-4Ts}}{s} - \frac{2e^{-5Ts}}{s} + \dots \\
 &= \frac{2}{s} \left[1 - e^{-Ts} + e^{-2Ts} - e^{-3Ts} + e^{-4Ts} - e^{-5Ts} + \dots \right] \\
 &= \frac{2}{s} \left[1 + e^{-Ts} \right]^{-1} = \frac{2}{s} \left(\frac{1}{1 + e^{-Ts}} \right)
 \end{aligned}$$

Another method

The given waveform is periodic with period $2T$.



periodicity property

$$X(s) = \frac{1}{1 - e^{-2Ts}} X_1(s)$$

$$x_1(t) = 2 [u(t) - u(t-T)]$$

$$x_1(s) = 2 \left(\frac{1}{s} - \frac{e^{-Ts}}{s} \right) = \frac{2}{s} (1 - e^{-Ts})$$

$$X(s) = \frac{1}{1 - e^{-2Ts}} \left(\frac{2}{s} (1 - e^{-Ts}) \right)$$

$$= \frac{2}{s} \cdot \frac{1 - e^{-Ts}}{(1 + e^{-Ts})(1 - e^{-Ts})} = \frac{2}{s} \left(\frac{1}{1 + e^{-Ts}} \right)$$

periodicity property:

Used in determining the transform of periodic time functions.

$x(t) = x(t+nT)$, where T is period, $n=0,1,2,\dots$

$$X(s) = \int_0^{\infty} x(t) e^{-st} dt$$

$$X(s) = \int_0^T x(t) e^{-st} dt + \int_T^{2T} x(t) e^{-st} dt + \int_{2T}^{3T} x(t) e^{-st} dt + \dots + \int_{nT}^{(n+1)T} x(t) e^{-st} dt + \dots$$

$$= \int_0^T x(t) e^{-st} dt + e^{-sT} \int_0^T x(t+T) e^{-st} dt + \dots + e^{-nsT} \int_0^T x(t+nT) e^{-st} dt$$

$$x(t) = x(t+T) = x(t+2T) \dots$$

$$x(s) = \int_0^T x(t) e^{-st} dt + e^{-sT} \int_0^T x(t) e^{-st} dt + \dots + e^{-nsT} \int_0^T x(t) e^{-st} dt + \dots$$

$$= [1 + e^{-sT} + e^{-2sT} + \dots + e^{-nsT}] \int_0^T x(t) e^{-st} dt$$

$$= [1 - e^{-sT}]^{-1} \int_0^T x(t) e^{-st} dt = \frac{1}{1 - e^{-sT}} x_1(s).$$

$$\text{where } x_1(s) = \int_0^T x(t) e^{-st} dt$$